Parameterisable full-rotation actuator for adjusting dampers and disks in technical building installations

- Air damper size up to approx. $0.6 \mathrm{~m}^{2}$
- Nominal torque 3 Nm
- Nominal voltage AC/DC 24 V
- Control Modulating DC (0)2... 10 V Variable
- Position feedback DC 2... 10 V Variable
- Spindle driver Form fit 12 mm or 8 mm (with insert)


Technical data

| Electrical data | Nominal voltage | AC/DC 24 V |
| :---: | :---: | :---: |
|  | Nominal voltage frequency | $50 / 60 \mathrm{~Hz}$ |
|  | Nominal voltage range | AC 19.2...28.8 V / DC 21.6...28.8 V |
|  | Power consumption in operation | 2.5 W |
|  | Power consumption in rest position | 1.2 W |
|  | Power consumption for wire sizing | 5 VA |
|  | Connection supply / control | Cable $1 \mathrm{~m}, 4 \times 0.75 \mathrm{~mm}^{2}$ |
|  | Parallel operation | Yes (note the performance data) |
| Functional data | Torque motor | Min. 3 Nm |
|  | Torque variable | 25\%, 50\%, $75 \%$ reduced |
|  | Positioning signal Y | DC 0... 10 V |
|  | Positioning signal Y note | Input impedance $100 \mathrm{k} \Omega$ |
|  | Control signal Y variable | Open-close |
|  |  | 3-point (AC only) |
|  |  | Modulating (DC 0... 32 V ) |
|  | Operating range Y | DC 2... 10 V |
|  | Operating range Y variable | Start point DC $0.5 \ldots 30 \mathrm{~V}$ End point DC 2.5... 32 V |
|  | Position feedback U | DC $2 . .10 \mathrm{~V}$ |
|  | Position feedback U note | Max. 0.5 mA |
|  | Position feedback U variable | Start point DC 0.5... 8 V |
|  |  | End point DC 2.5... 10 V |
|  | Position accuracy | $\pm 5 \%$ |
|  | Direction of motion motor | Selectable with switch 0 / 1 |
|  | Direction of motion note | $\mathrm{Y}=0 \mathrm{~V}$ : At switch position 0 (ccw rotation) / 1 (cw rotation) |
|  | Direction of motion variable | Electronically reversible |
|  | Manual override | Gear disengagement with push-button, can be locked |
|  | Angle of rotation | 0...1800 ${ }^{\circ}$ |
|  | Angle of rotation note | Mechanical: 0... $330^{\circ}$, adjustable in $10^{\circ}$ increments; electronical: $0 . . .1800^{\circ}$, adjustable in $1^{\circ}$ increments |
|  | Running time motor | $150 \mathrm{~s} / 360^{\circ}$ |
|  | Motor running time variable | $70 . .280 \mathrm{~s} / 360^{\circ}$ |
|  | Adaption setting range | manual |
|  | Adaption setting range variable | No action |
|  |  | Adaption when switched on |
|  |  | Adaption after pushing the gear disengagement button |
|  | Override control | MAX (maximum position) $=100 \%$ |
|  |  | MIN (minimum position) $=0 \%$ |
|  |  | ZS (intermediate position, AC only) $=50 \%$ |
|  | Override control variable | MAX $=($ MIN + 32\%).. $.100 \%$ |
|  |  | MIN $=0 \% \ldots(\mathrm{MAX}-32 \%)$ |
|  |  | ZS = MIN...MAX |
|  | Sound power level motor | $45 \mathrm{~dB}(\mathrm{~A})$ |
|  | Spindle driver | Form fit 12 mm or 8 mm (with insert) |
| Safety | Protection class IEC/EN | III Safety extra-low voltage |

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- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea)water, snow, ice, insolation or aggressive gases interfere directly with the actuator and that is ensured that the ambient conditions remain at any time within the thresholds according to the data sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Mechanical interfaces which are not expressly provided by Belimo for this actuator must not be attached.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation site and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.


## Product features

Mode of operation The actuator is connected with a standard modulating signal of DC $0 \ldots .10 \mathrm{~V}$ and drives to the position defined by the positioning signal. Measuring voltage $U$ serves for the electrical display of the damper position $0 . . .100 \%$ and as slave control signal for other actuators.
Parameterisable actuators
The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.
Simple direct mounting Form-fit direct mounting on a 12 mm or 8 mm damper spindle (with insert). The actuator can also be optionally equipped with a 10 mm form fit or an $8 . . .12 \mathrm{~mm}$ clamp (see «Accessories»).
Manual override Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).

High functional reliability The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Adjustable angle of rotation
The angle of rotation of the full-rotation actuator can be adjusted in $10^{\circ}$ increments between 0 and $330^{\circ}$ with angle of rotation limiter ZDB-LU.

Home position The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0\%).
The actuator then moves into the position defined by the positioning signal.


Adaption and synchronisation
An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range).
Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0\%).
The actuator then moves into the position defined by the positioning signal.
A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

## Accessories

|  | Description | Type |
| :---: | :---: | :---: |
| Electrical accessories | Signal converter voltage/current, supply AC/DC 24V | Z-UIC |
|  | Digital position indicator for front-panel mounting, 0...99\%, front mass $72 \times 72 \mathrm{~mm}$ | ZAD24 |
|  | Range controller for wall mounting, adjustable electron. Min./max. angle of rotation limitation | SBG24 |
|  | Positioner for wall mounting, range 0...100\% | SGA24 |
|  | Positioner in a conduit box, range 0...100\% | SGE24 |
|  | Positioner for front-panel mounting, range 0...100\% | SGF24 |
|  | Positioner for wall mounting, range 0... $100 \%$ | CRP24-B1 |
|  | Connecting cable $5 \mathrm{~m}, \mathrm{~A}+\mathrm{B}$ : RJ12 6/6, To ZTH/ZIP-USB-MP | ZK1-GEN |
|  | Connection cable 5 m, A: RJ11 6/4, B: Free wire end, To ZTH/ZIP-USB-MP | ZK2-GEN |
|  | Description | Type |
| Mechanical accessories | Spindle clamp LU.. for clamping range 8... 12 mm | K-LU |
|  | Angle of rotation limitation LU.., with scaling $0 . . .330^{\circ}$ | ZDB-LU |
|  | Form fit insert 10x10 mm, for LU.. | ZF10-LUA |
|  | Description | Type |
| Service Tools | Service Tool, for MF/MP/Modbus/LonWorks actuators and VAVController | ZTH EU |
|  | Belimo PC-Tool, software for adjustments and diagnostics | MFT-P |
|  | Adapter to Service-Tool ZTH | MFT-C |

Notes $\quad$ - Connection via safety isolating transformer.

## Wiring diagrams

AC/DC 24 V , modulating


> Cable colours:
> $1=$ black
> $2=$ red
> $3=$ white
> $5=$ orange

Parallel operation


## Notes

- A maximum of eight actuators can be connected in parallel.
- Parallel operation is permitted only on non-connected axes.
- Do not fail to observe performance data with parallel operation.


## Functions

## Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts


Override control with AC 24 V with rotary switch


Remote control 0...100\% with Minimum limit with positioner SG.. positioner SG.


## Functions

Position indication


Functional check


Control with $4 . . .20 \mathrm{~mA}$ via external resistor


Caution:
The operating range must be set to DC 2... 10 V .
The $500 \Omega$ resistor converts the $4 . . .20 \mathrm{~mA}$ current signal to a voltage signal DC $2 \ldots 10 \mathrm{~V}$

## Functions for actuators with specific parameters (Parametrisation with PC-Tool necessary)

Override control and limiting with AC 24 V with relay contacts


Control open-close


Y (DC 0... 10 V )


Control 3-point


- U


1) Caution: This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V .

## Operating controls and indicators


(1) Direction of rotation switch

Switch over: Direction of rotation changes
(2) Push-button and LED display green

Off: $\quad$ No power supply or malfunction
On: In operation
Press button: Triggers angle of rotation adaptation, followed by standard mode
(3) Push-button and LED display yellow

Off: Standard mode
On: Adaptation or synchronising process active
Press button: No function
(4) Gear disengagement button

Press button: Gear disengages, motor stops, manual override possible
Release button: Gear engages, synchronisation starts, followed by standard mode

## (5) Service plug

For connecting parameterisation and service tools
Check power supply connection
(2) Off and 3 On Possible wiring error in power supply

Service
A Notes • The actuator can be parameterised by PC-Tool and ZTH EU via the service

Service Tools connection ZTH EU connection


PC-Tool connection


## Dimensions [mm]

Spindle length


Clamping range


## Dimensional drawings




