

Volume IV

Final
Report

September 1972

Program Development
Requirements

**Astronomy
Sortie
Missions
Definition
Study**



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Volume IV

Final
Report

September 1972

**ASTRONOMY
SORTIE MISSION
DEFINITION STUDY**

**ASTRONOMY SORTIE PROGRAM
PROGRAM DEVELOPMENT
REQUIREMENTS**

Prepared for:

National Aeronautics and Space Administration
George C. Marshall Space Flight Center
Huntsville, Alabama

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FOREWORD

This document is submitted in accordance with the Data Procurement Document Number 282, Data Requirement Number MA-04 under the George C. Marshall Space Flight Center Contract NAS8-28144.

This is the fourth of four volumes of the Astronomy Sortie Missions Definition Study Final Report. This volume contains the program development requirements.

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PREFACE

The realization of a fully operational Space Shuttle will open the door for unparalleled research opportunities in space astronomy. One mode of operation currently envisioned for the Space Shuttle is the short-duration sortie mission. The sortie mission would consist of a low earth orbit of approximately seven days' duration. During this seven days, research would be conducted by an experiment crew utilizing a scientific payload located in the Space Shuttle cargo bay.

For research in astronomy, the Space Shuttle sortie mission offers significant advantages. Several of the more important are (1) the ability to escape the Earth's atmosphere and, therefore, open up the entire electromagnetic spectrum to research, (2) the elimination of atmospheric perturbations and, thus, the ability to use the spatial resolution of the telescopes, which is currently limited to approximately one-half arc-second for ground-based telescopes, and (3) the ability to continually observe the sun during the seven-day mission without obscurations. Combining these scientific advantages with the large payload capability of the Space Shuttle, the low-cost operation of the Space Shuttle, the availability of an experiment crew on-orbit with the experiments, the frequent space flight opportunities, and the ability to return the experiment to Earth for refurbishment and retrofit offer the scientific community a unique opportunity for further research in the field of astronomy.

While the opportunities for advances in space astronomy research are clear, it is evident that significant planning is required by NASA to ensure an orderly and timely program that not only satisfies the astronomy objectives but also provides the most return for the smallest investment. The primary purpose of this study was to provide NASA with an overview of the astronomy sortie mission requirements.

The specific objectives of the study were to:

- 1) Evaluate the responsiveness of the sortie mission concept to stated scientific objectives;
- 2) Develop conceptual designs and interfaces for sortie missions including telescopes, mounts, controls, displays, and support equipment;

- 3) Develop a system concept encompassing the sortie mission from mission planning through postflight engineering and scientific documentation;
- 4) Provide funding estimates, development schedules, and supporting research and technology requirements for Shuttle sortie hardware.

The approach used in performing the study consisted of the following sequence:

- 1) Analyzing and conceptually designing the alternative candidate astronomy sortie mission program that maximized the utilization of common features;
- 2) Analyzing the astronomy sortie mission program to ensure compatibility between interfacing systems, evaluating overall performance and ensuring mission responsiveness, and developing a complete mission profile;
- 3) Analyzing the support subsystems to a depth sufficient to establish feasibility, compatibility with other subsystems, adequate performance, physical characteristics, interface definition, reliability level, and compatibility with manned operations;
- 4) Conceptually designing the selected astronomy sortie mission program, which included defining the significant design features, dimensions and interfaces on layout drawings, and defining the telescope system physical characteristics and support requirements;
- 5) Providing funding estimates, development schedules, and supporting research and technology requirements.

The final report of the study is contained in four volumes of which this volume is Volume II, Book 1. They are:

Volume I - *Astronomy Sortie Missions Definition Study Final Report: Executive Summary*

This volume summarizes the significant achievements and activities of the study effort.

Volume II - *Astronomy Sortie Missions Definition Study Final Report:*

Book 1 - *Astronomy Sortie Program Technical Report*

Book 1 of this volume includes the definition of telescope requirements, preliminary mission and system definitions, identification of alternative sortie programs, definition of alternative sortie programs, evaluation of the alternative sortie programs, and selection of the recommended astronomy sortie mission program. This volume identifies the various concepts approached and documents the rationale for the concept and approaches selected for further consideration.

Volume II - *Astronomy Sortie Missions Definition Study Final Report:*

Book 2 - *Appendix*

Book 2 of this volume contains the *Baseline Experiment Definition Documents* (BEDDs) that were prepared for each of the experiments considered during the study.

Volume III - *Astronomy Sortie Missions Definition Study Final Report:*

Book 1 - *Design Analyses and Trade Studies*

Book 1 of this volume includes the results of the design analyses and tradeoff studies conducted for candidate concepts during the selection of recommended configurations as well as of the design analyses and tradeoff studies conducted for the selected concept.

Volume III - *Astronomy Sortie Missions Definition Study Final Report*

Book 2 - *Appendix*

Book 2 of this volume contains the backup or supporting data for the design analyses and tradeoff studies that are summarized in Volume III, Book 1.

Volume IV - *Astronomy Sortie Missions Definition Study Final
Report: Program Development Requirements*

This volume contains the planning data for subsequent phases and includes the gross project planning requirements; schedules, milestones, and networks; supporting research and technology; and cost estimates.

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INTRODUCTION

Program development requirements for the selected Astronomy Sortie missions concept were generated and are presented in this volume in four parts as follows: Part I identifies the gross planning requirements that must be considered in subsequent phases of the project; Part II presents the schedules and logic networks for the design, development, and operation of the overall project; Part III identifies the supporting research and technology required to support the project; and Part IV presents the cost estimates of the selected concept, including development and the 12-year operations program.

Data reported in each part includes the appropriate rationale with explanations of the guidelines and assumptions that were used in the analyses and estimates.

I. PROJECT PLANNING REQUIREMENTS

A. INTRODUCTION

The gross planning requirements for subsequent phases of the Astronomy Sortie mission (ASM) project are presented here. The requirements were derived in five areas: (1) engineering and manufacturing; (2) testing; (3) quality and reliability assurance; (4) facilities; and (5) project management.

These requirements are not intended to limit future analyses in either scope or depth. Rather, these requirements are the essential elements that must be considered (or provided) to synthesize an effective program that satisfies the objectives economically and on schedule.

B. ENGINEERING AND MANUFACTURING

The ASM telescopes and arrays are one-of-a-kind experiments that impose unique standards on design, fabrication, and acceptance for flight. Further, these telescopes and arrays will be used over a period of up to 12 years for several missions each. Thus, it is desirable that the telescopes and arrays be capable of accommodating new detectors, filters, cameras, and systems to exploit scientific advances developed during the operations phase of the project. The total number of seven-day Sortie missions for each experiment is shown in the following tabulation.

Telescopes	Number of Flights	Arrays	Number of Flights
IR	31	Large Area X-Ray Detector	13
Stratoscope III	24	Wide Coverage X-Ray	55
Photoheliograph	26	Large Modulation Collimator	14
X-Ray Telescope	26	Narrow Band Spectrometer Polarimeter	14
XUV Spectroheliograph	26	Collimated Plane Crystal Spectrometer	13
Coronagraphs	26	Gamma-Ray Spectrometer Low Background Gamma-Ray Detector	14 14

Subsystems are needed for each Sortie Lab and pallet payload, requiring the use of several flight units and spares to support the 12-year operations phase. Provision must be made for initial fabrication of spares whenever possible, since it is impractical to maintain manufacturing capabilities over long periods of time. Engineering considerations must include the requirements of long-term storage of spares, allowing for the performance degradation effects of time and maintaining cleanliness, configuration control, and production acceptance status.

C. TESTING

The overall test program will verify the compatibility of Astronomy Sortie payloads with the Shuttle interfaces and will validate the design and development of the payloads, assuring reliable experiments that fulfill their Sortie mission objectives. Testing (and analyses) during the design development phases will accurately predict and verify failure modes as well as the stress levels at which failures occur. Stress levels refer to the intensity and duration of any parameter that affects the ability of a component, system, or complete payload to perform its design function, and includes both imposed environments and self-induced conditions.

Development and test of experiments, subsystems, and payloads will fully exploit existing space-qualified hardware, military-qualified hardware, and commercial airline hardware, giving consideration to the individual Sortie mission duration, the number of missions in the program (for that payload or experiment), and the maintenance and refurbishment that is possible between missions. Validation of hardware capabilities to meet payload objectives will require extensive systems engineering analysis, previous test results, and previous use. The inherent capabilities of hardware will be determined by thorough examination of systems design, failure mode and effects analyses, and demonstrated performance under imposed environments. Capabilities will then be compared with operating requirements and environments for these Sortie missions. Additional testing will be concentrated on resolving those uncertainties that systems design and previous test analyses have not satisfied.

Performance that requires verification over the complete mission environments of temperature, vacuum, acceleration, vibration, and acoustics will be certified by methods other than test wherever possible. Methods will consist of one or a combination of the following items.

1. Similarity

Testing will be waived if it can be demonstrated that the item is similar or identical in design and manufacturing processes to another article that has previously been tested to equal or more stringent limits.

2. Analyses

Analytical techniques will be used in lieu of testing to certify compliance with specified requirements. Analyses may include systems engineering studies, statistics, qualitative reviews, and computer assisted modeling and simulations.

3. Demonstration

Some features of payloads or experiments, such as access for servicing or adjustment, and human engineering factors, will be certified by demonstrating that the payload or experiment operates properly.

4. Test Exercises

Tests will verify proper operation of payload or experiment equipment not certified by similarity, analyses, or demonstration. Tests will be run (when required) on hardware that has satisfactorily passed requirements for acceptance. Tests will include exposure to environments or loads in excess of those maximums expected in a mission, or for durations longer than expected to certify that critical systems will not impose any detrimental effect on the Orbiter or crew. Noncritical systems will be tested to limits as required by the detail specifications.

D. QUALITY AND RELIABILITY ASSURANCE

1. Quality Assurance

The ASM project includes experiment hardware developed by experiment contractors and principal investigators not always experienced in the fabrication and integration of space hardware. Further, the program provides for return of payloads from orbit, permitting refurbishment and modification of experiments on the ground prior to a later mission. These project requirements will be extended over the 12-year duration of operations, plus the preoperational phases, and impose the need for a comprehensive and continuing quality assurance program.

It is intended that established quality techniques, methods, and management will be used to ensure that the engineering, hardware, and operations support from the different experiment contractors are integrated to provide a flight-ready payload at the PIC-MSFC and at the launch site so that maximum mission success is achieved within cost and schedule constraints. Contamination control of the experiment hardware will be a major challenge to the quality assurance program for the design and hardware phases of the program.

2. Reliability

The reliability program will place primary emphasis on the identification of all single failure points in the payloads that are critical to crew safety and/or mission success. The most cost-

effective means of eliminating or reducing the effects of these critical failures will be determined. The basic reliability program philosophy will be to require redundancy only for safety-critical items or where the cost of incorporation into the design is very low. Inflight maintenance, degraded modes of operations, or return to earth for maintenance will be evaluated for all other cases. The reliability program will require the evaluation of all experiment hardware, support hardware, and interfaces that make up the payload. In addition, this program will consider the effects that integrating the hardware at the PIC-MSFC, transportation to the launch site, and installation in the Orbiter may have on mission reliability.

E. FACILITIES

Existing Government or contractor facilities will be used as much as possible to minimize modification and construction of new buildings, laboratories, clean rooms, test chambers, etc.

The telescopes and arrays will be developed and built by principal investigators or experiment contractors and will be provided to NASA in a flight-ready condition for integration into the Sortie Lab and pallet. Facilities necessary for experiment integration will be identified and coordinated with facility requirements for other project phases.

The subsystems will be developed and fabricated by the contractor and will be integrated into the Sortie Lab and pallet at the PIC-MSFC. Facilities necessary for development, manufacture, and acceptance for integration, as well as those required for integration of the subsystems into the Sortie Lab and pallet will be identified and coordinated for time-phased needs, candidate existing installation, and interference with other projects.

Facilities planning must cover the 12-year operations period for all phases of the missions. Of particular concern is the refurbishment phase in which capabilities to support the telescopes and arrays as well as the subsystems must be provided at the PIC-MSFC. Storage and control of subsystem spares for the duration of this project may impose unique requirements that must be identified for analysis of the impact on facilities.

F. PROJECT MANAGEMENT

Project management requirements for ASM include defining subsequent phase study tasks, objectives, and schedules. These tasks must be coordinated with the Shuttle studies in progress and with other experiment and payload studies on a continuing basis.

Coordination of the project with the astronomy scientific community is necessary and requires liaison to identify objectives and define methods of performance.

Program control, progress reporting, and problem solving require definition of milestone objectives that may be restated periodically. Control techniques must be imposed on subcontractors with effective communications.

The changing depths of analyses in subsequent phases of the program require review of responsibilities and manpower skills applied to the tasks. Management must develop a logical sequence of work to ensure synthesis of the concepts into systems characteristics definition.

II. SCHEDULES, MILESTONES, AND NETWORKS

A. INTRODUCTION

All elements of the work breakdown structure (WBS) for the ASM program are included in the total program schedules presented here. Schedules were developed for the total system, identifying individual schedules for each flight hardware item at levels 5 and 6 on the WBS.

B. PROGRAM MILESTONE SCHEDULE

The program schedule shown in Fig. II-1 begins with the issuance of the RFP for a Phase B study. This program schedule is based on the program flight schedule shown in Fig. II-2 for the baseline payload combinations. During the Phase B study period, authorization to proceed for long-lead-time (LLT) development of telescopes and arrays are scheduled. The ASM program contract award is scheduled for January 1975 with the first flight, a solar mission, scheduled in the first quarter of 1979.

The telescopes, arrays, and subsystems will be accepted for integration at the contractor that develops and builds them and will be delivered to MSFC for integration into the Sortie Lab and pallet. Six months of integration and test activity for the first solar flight is scheduled. The totally integrated Sortie Lab and pallet, with subsystems and experiments, is then loaded in the Super Guppy and delivered to the launch site for three months of prelaunch operation before the first flight.

Eighty-one flights, beginning in the first quarter of 1979 and ending in 1990, are planned. The first flights of the three basic configurations are:

Solar (26 flights), 1st quarter 1979;

IR (31 flights), 4th quarter 1979;

Stratoscope III (24 flights), 1st quarter 1982.

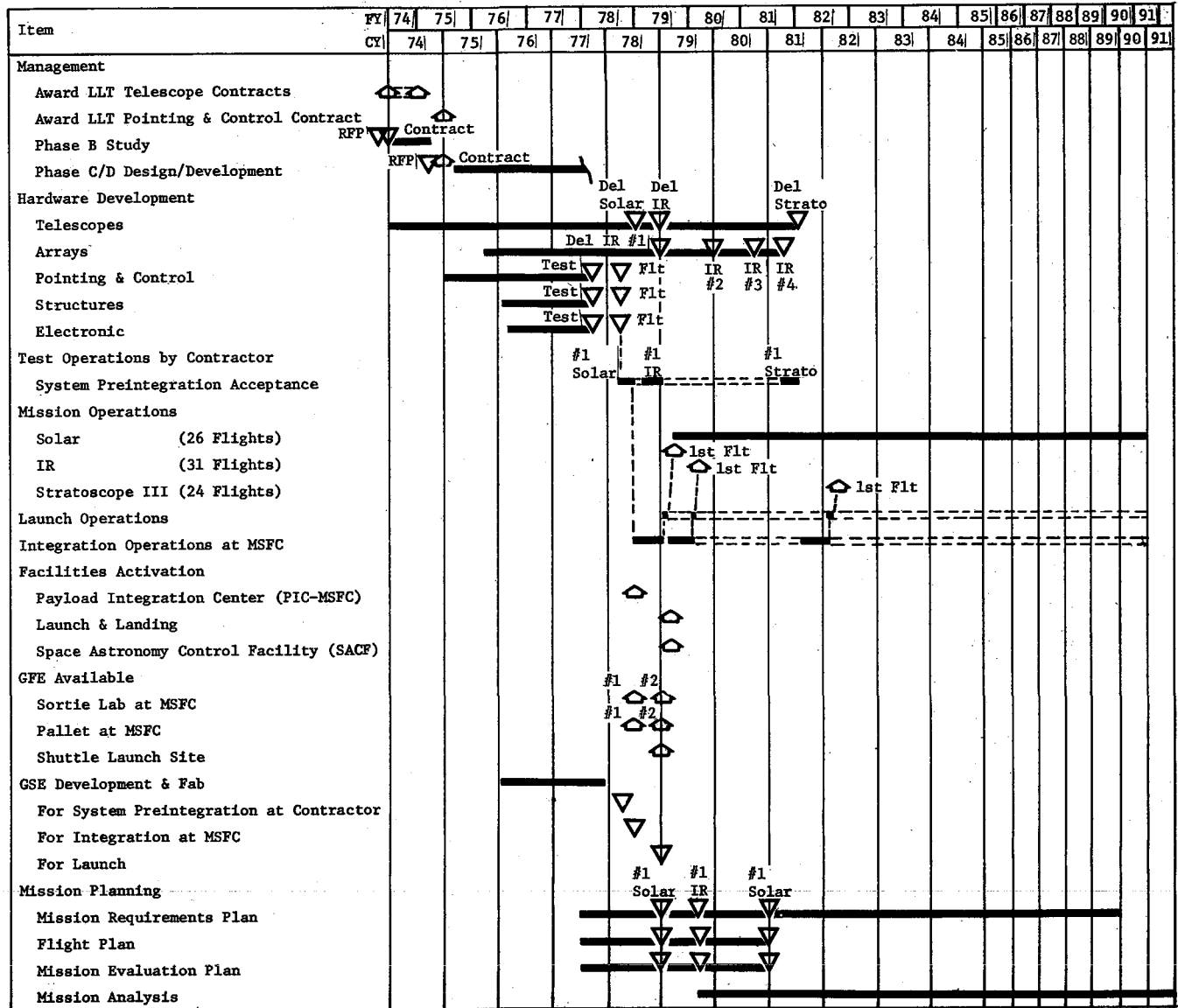


Fig. II-1 Program Milestones Schedule.

Payload		Calendar Year											Total	
		79	80	81	82	83	84	85	86	87	88	89		90
Solar 1-2		X	XX	XXX	XXX	XXX	XX	XX	XX	XX	XX	XX	XX	26
Strato- scope III	3AB				X		X	X		X	X	X		6
	3AC						X	X	X		X	X	X	6
	3AD					X	X		X	X	X		X	6
	3AE					X		X	X	X		X	X	6
IR	4AB		X		X	X		X	X		X	X	X	8
	4AC	X			X	X	X		X	X	X		X	8
	4AD			X	X		X	X		X	X	X	X	8
	4AE			X		X	X	X	X	X		X		7
Total		2	3	5	7	8	8	8	8	8	8	8	8	81

Fig. II-2 Program Flight Schedule

The payloads are returned after each flight. The Sortie Lab and pallet with experiments is then shipped to the Payload Integration Center (PIC) at MSFC, the experiments are removed, and the Sortie Lab and pallet are refurbished to receive other experiments. After integration of other telescopes and arrays, the integrated payload is tested and accepted as flight-ready. The payload is then shipped to the launch site for another Sortie flight.

Flight payloads do not pass through the Space Astronomy Control Facility (SACF). Film exposed in missions will be returned to the SACF for processing, and scientists there must have communications with the flight (through mission control), but the payload handling capabilities necessary at the PIC-MSFC and at launch site are not needed at SACF. The overall turnaround time for a payload to complete one flight and be refurbished ready for another flight, is ten weeks, as shown in Fig. II-3. To meet the flight schedule of 81 flights during the 12-year period, two complete Sortie Labs and pallets are required.

C. FACILITIES AND GSE

The primary facilities to be activated are the PIC-MSFC, the launch and landing site, and the SACF (Fig. II-4). These facilities will be outfitted with GSE developed concurrently with the flight hardware by the hardware manufacturer, and payload handling and support equipment GSE developed by the program contractor.

D. LAUNCH, MISSION, AND RECOVERY/REFURBISHMENT OPERATIONS

Eighty-one flights, each lasting one week, are scheduled beginning early in 1979 and ending in 1990 as shown in Figure II-5. The reusable flight hardware is planned to be refurbished on a ten-week turnaround period with refurbishment operations performed at the PIC-MSFC.

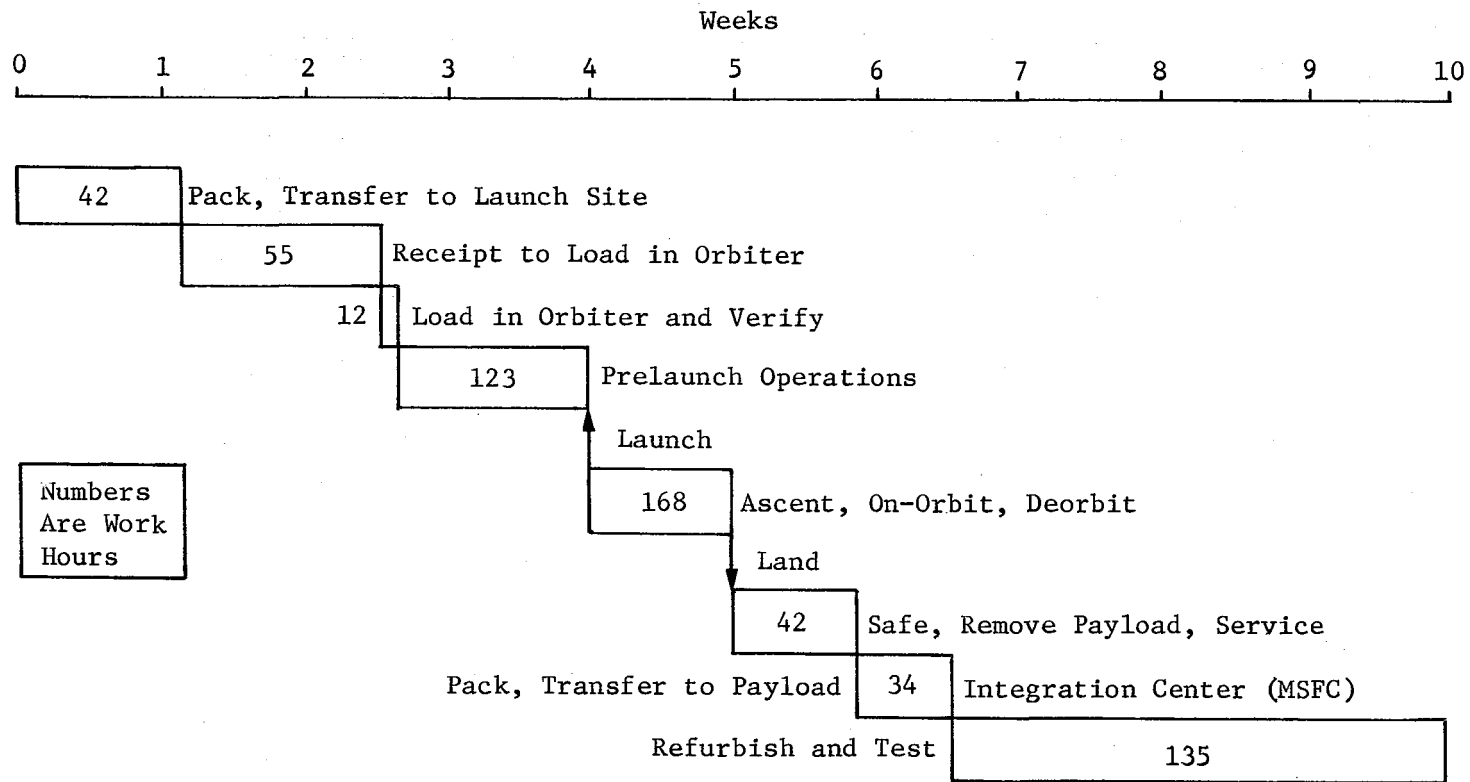


Fig. II-3 Turnaround Schedule

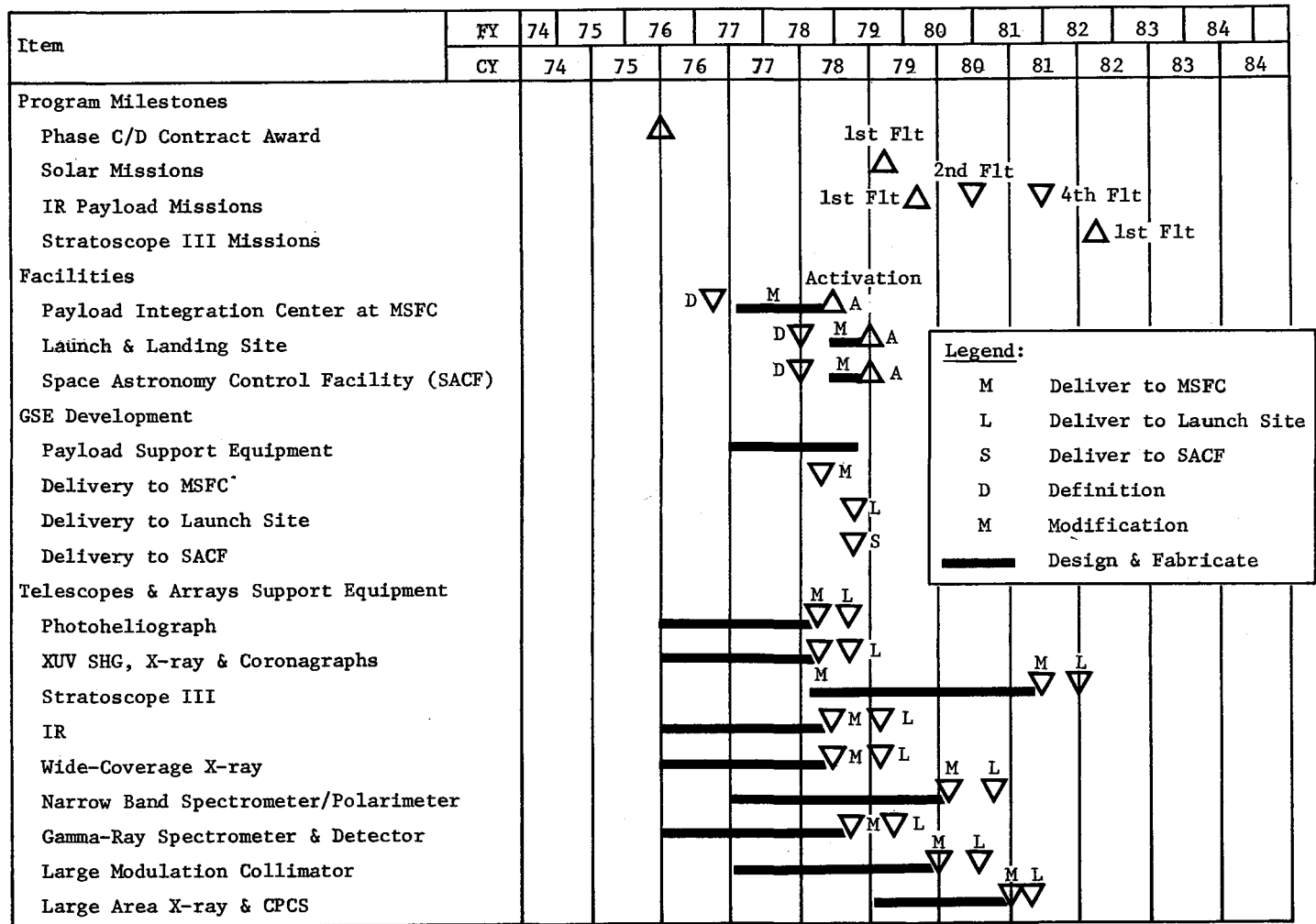


Fig. II-4 Facilities and GSE Schedule

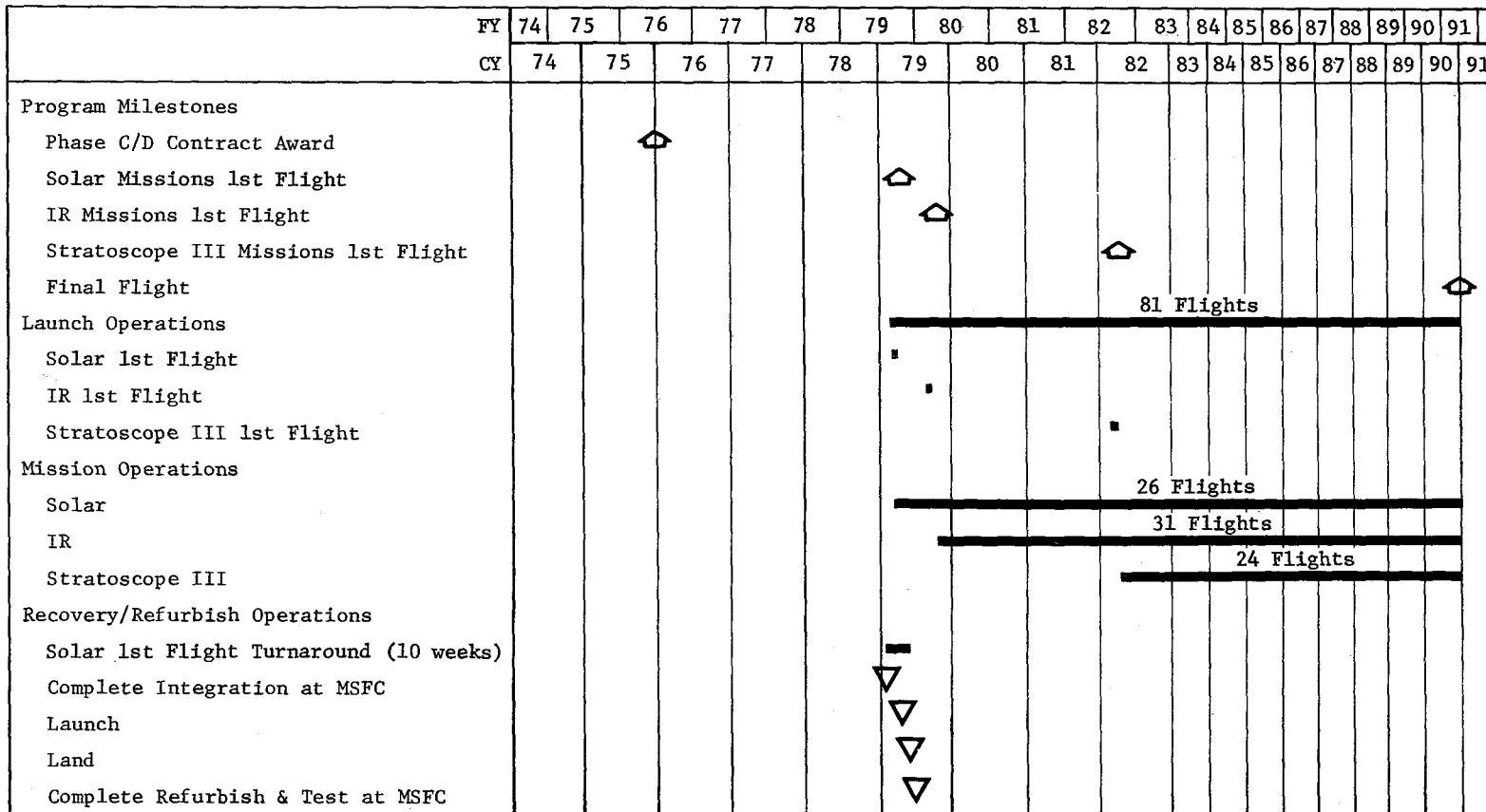


Fig. II-5 Launch, Mission, and Recovery/Refurbishment Operations Schedule

E. TELESCOPES AND ARRAYS

These experiments will be built using a single article approach in which the flight unit will be subjected to any development tests after which it will be modified and serviced for flight acceptance. It is expected that each telescope and array will be contracted for individually by NASA and provided to this project. In some cases schedule dates shown in Fig. II-6 and II-7 require ATP before Phase C/D contract award to meet integration, check-out, and the first Astronomy Sortie flight.

F. POINTING AND CONTROL, STRUCTURES, ELECTRONICS, AND THERMAL SUBSYSTEMS

Test and flight articles are required for these subsystems (see Fig. II-8). The test article will be used by the project contractor in conducting systems tests (structural loading, dynamic, natural environments, and limited function) at the contractor's plant. The flight unit will undergo pre-integration acceptance tests before shipment to the PIC-MSFC where integration with the Sortie Lab and pallet is performed. The pointing and control system is the long-lead time development item and will require authorization to proceed concurrently with the Phase C/D program contractor award.

G. MILESTONE LOGIC NETWORK

Using the schedules as a guide, the logic network shown in Fig. II-9 was developed. No prerequisite event problem areas appear in either project development or operations. However, SRT tasks need to be started in early calendar year 1973 to support the subsystems DDT&E.

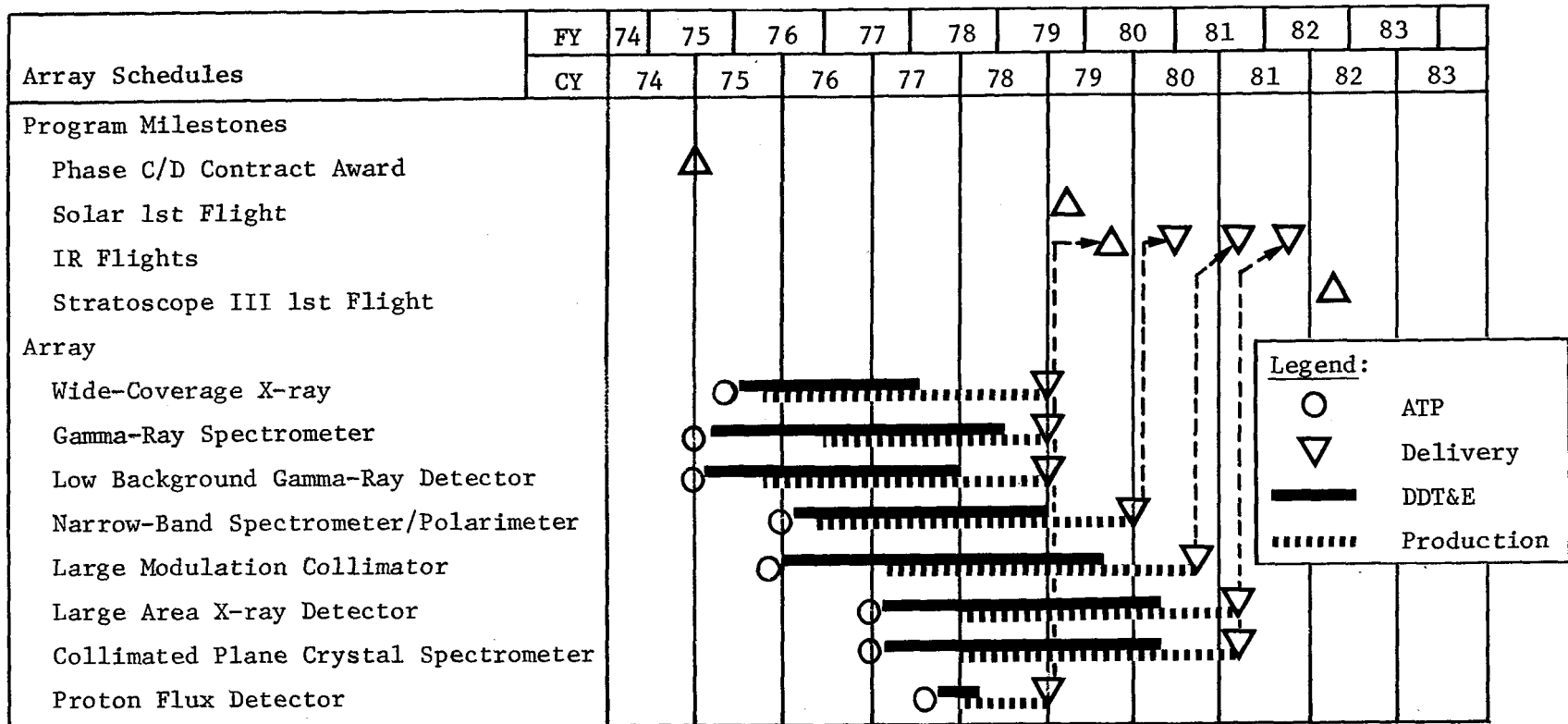


Fig. II-7 Arrays Schedule

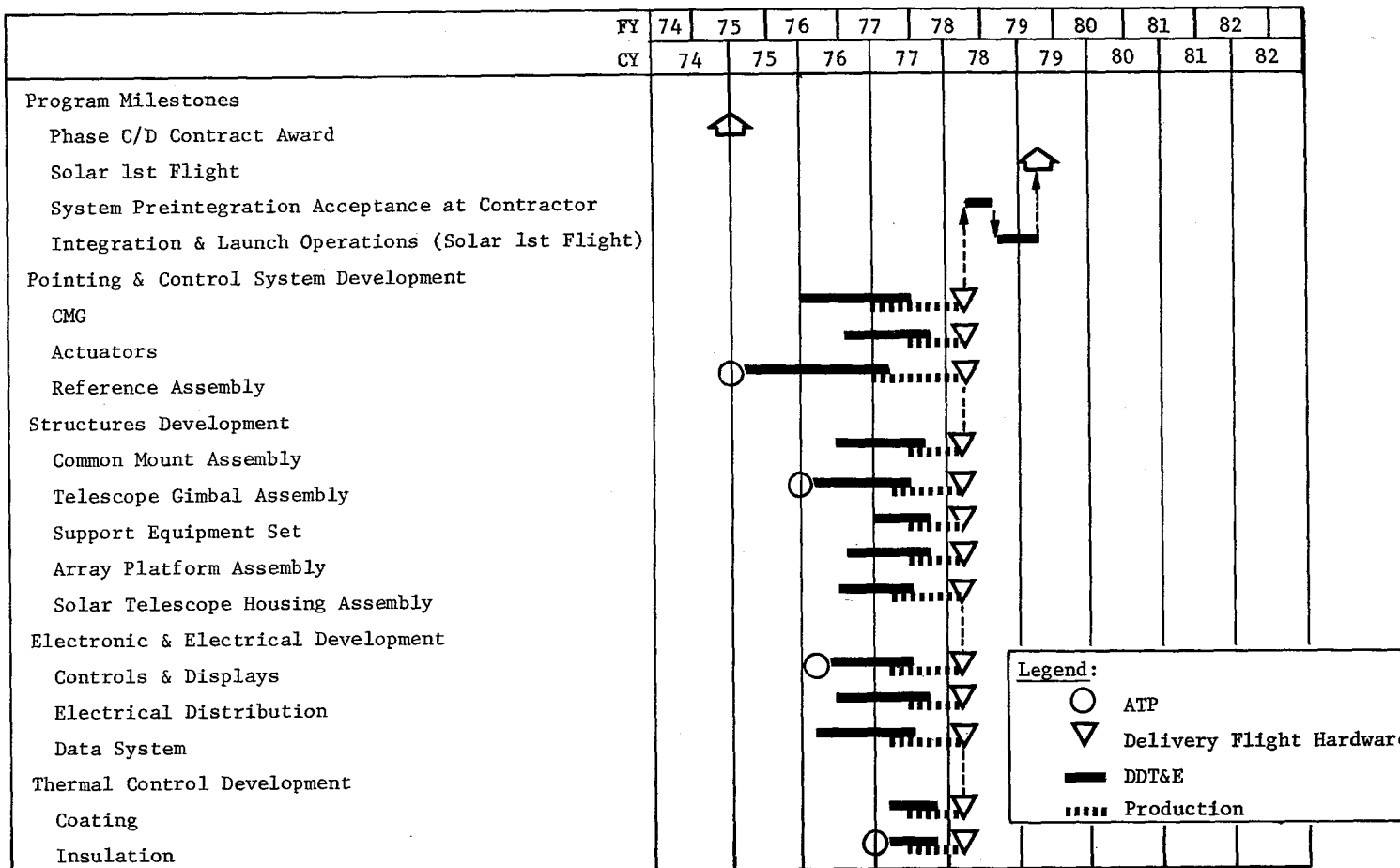


Fig. II-8 Pointing and Control, Structures, Electronics, and Thermal Subsystems Schedule

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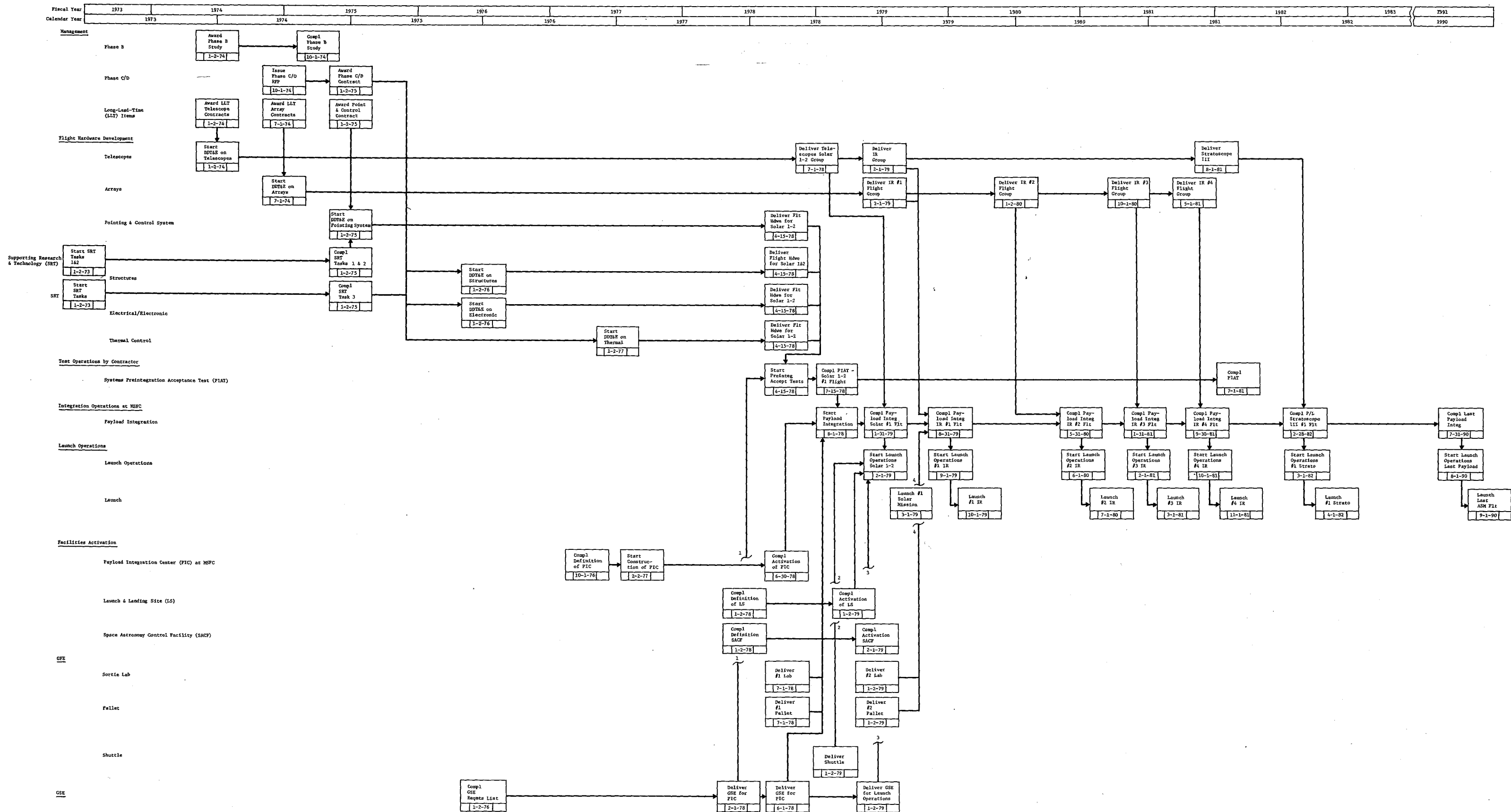


Fig. 11-9 Milestone Logic Network 11-13

III. SUPPORTING RESEARCH AND TECHNOLOGY

A. INTRODUCTION

Supporting research and technology has been defined for the subsystems, assemblies, and components. Detailed requirements are presented in Section B of this part.

In the telescopes and arrays, some technology requirements have been identified by title, but detailed definitions have not been made. The following items are examples of these requirements:

- 1) Aspheric grating for the XUV spectroheliograph;
- 2) IR detector compatible with the 2°K operating temperature;
- 3) Cooling equipment systems for the IR telescope, requiring 30°K, and for the IR detector, which should be cooled to 2°K;
- 4) Equipment systems for controlling contamination of critical surfaces of telescopes.

B. SUPPORTING RESEARCH AND TECHNOLOGY (SRT) REQUIREMENTS

Three SRT tasks for the subsystems have been identified. They are: (1) telescope fine stabilization actuators; (2) precision star trackers; and (3) contamination control and countermeasures.

1. SRT Requirement No. 1

a. Title - Telescope Fine Stabilization Actuators

b. Status - The external stability design goals for the ASM telescopes are 0.5 μ rad (0.1 $\widehat{\text{sec}}$) in azimuth and elevation and 25 μ rad (5 $\widehat{\text{sec}}$) in roll. The selected concept for the pointing and control system includes two separate subsystems to provide the external stabilization for the telescopes: (1) a double gimbal CMG subsystem to stabilize the Shuttle Orbiter in an X-POP attitude; and (2) a fine external telescope stabilization subsystem using flex-pivots to stabilize the telescopes in azimuth and elevation and a servoed roll ring to stabilize them in roll.

The flex-pivot actuators capable of providing these stability requirements have not been developed.

c. Justification - The state of the art for stabilizing telescopes attached to manned spacecraft is Skylab. The projected stabilization capability of this Skylab system as determined by computer simulation is $10 \mu\text{rad}$ (2sec) in azimuth and elevation.

The ASM external telescope stabilization goal of $0.5 \mu\text{rad}$ (0.1sec) is 20 times better than that of Skylab. Even this stringent ASM stability goal is not sufficient for the photoheliograph and Stratoscope III, however, and these two telescopes will augment the external stabilization systems using internal image motion compensation to meet their final required stability. Considering these requirements, and to account for stabilization errors due to thermal flexing of the telescopes, an improvement factor over Skylab of approximately 50, or a stability of $0.2 \mu\text{rad}$ (0.04sec), may be a justifiable goal. The baseline stability goal of $0.5 \mu\text{rad}$ (0.1sec) is beyond that of the present verified state of the art; however, and does meet ASM scientific requirements. Systems to provide this capability should be developed.

d. Technical Plan

Objectives - The objective of this task is to develop fine stabilization actuators, which, when integrated with reference assembly optics and electronics, will provide a stability of $0.5 \mu\text{rad}$ (0.1sec) in elevation and azimuth and $25 \mu\text{rad}$ (5sec) in roll.

Technical Approach - Feasibility analyses are required to determine systems interfaces and establish specific performance requirements. These analyses should produce preliminary design requirements from which shop drawings suitable for fabrication of initial engineering test units may be prepared. Engineering test units will be fabricated and operated under suitable environmental conditions and appropriate loads to evaluate the designs.

The results of these development tasks will be reported to the ASM project as requirements and preliminary specifications for use in design, development, test, and evaluation (DDT&E) of azimuth and elevation actuators for fine stabilization of the telescopes.

e. Resource Requirements

FY	1973	1974		1975
CY	1973		1974	
Manpower	2.5	5.0	6.0	4.0
Computer Hours	200	215		
Fab Shop		—————		
Test Lab			—————	
Funding	\$211,000	\$518,000		\$97,000

f. Target Schedule

FY	1973	1974		1975
CY	1973		1974	
Analyses	—————		△	
Design	—————	△		
Fabricate		—————	△	
Test			—————	△
Report				————— △

2. SRT Requirement NO. 2

a. Title - Precision Star Tracker

b. Status - To properly guide the high-resolution ASM telescopes, an absolute angular measurement (pointing) accuracy of $\pm 5 \mu\text{rad}$ ($\pm 1 \text{ sec}$) is required. An angle resolution (stability) of $0.5 \mu\text{rad}$ (0.1 sec) is required. These are considered design goals for the pointing and control system.

Precision star trackers capable of providing these requirements (when operated with appropriate actuators) have not been developed. Current state-of-the-art equipment achieves about $\pm 25 \mu\text{rad}$ ($\pm 5 \text{sec}$) absolute angle measurement accuracy with resolution of $10 \mu\text{rad}$ (2sec) according to developer's claims.

c. Justification - Several of the ASM telescopes require orienting of their optical axes to specific astronomical sources of interest to within $\pm 10 \mu\text{rad}$ ($\pm 2 \text{sec}$). This uncertainty is total system error and includes reference measurement errors and instrument-to-reference alignment errors.

Those ASM telescopes with resolution capability of $0.5 \mu\text{rad}$ (0.1sec) will additionally require further control of the image within the instruments.

The required accuracy and resolution are not available from any form of "strapdown" (nongimbaled) tracker system of reasonable size. The sensor field of view required for high probability of encountering stars of adequate brightness is far too large. Even for a gimbaled star tracker, with wide range of freedom for selecting reference stars, and limited instantaneous field of view, comparatively large (>20 cm diameter) primary objective apertures will be required to gather enough light energy from the brighter stars ($m_v < +4.5$) to provide star tracker system bandwidths higher than 10 Hz together with resolution of $0.5 \mu\text{rad}$ (0.1sec).

d. Technical Plan

Objective - Development of a star tracker system capable of defining the orientation of the instrument platform with an absolute accuracy of $\pm 5 \mu\text{rad}$ ($\pm 1 \text{sec}$) relative to specified stars. The tracker bandwidth must be at least 10 Hz; the angular resolution performance must be $0.5 \mu\text{rad}$ (0.1sec) or better.

Technical Approach - The development of telescope fine stabilization actuators (SRT Requirement No. 1) is a related requirement that must be accomplished concurrently with this star tracker task. In addition to these actuators, three specific items may be identified that require fundamental development effort:

Angular measuring devices (e.g., autosyns, optical encoders, optosyns, etc) with absolute accuracy of $\pm 2.5 \mu\text{rad}$ ($\pm 0.5 \text{sec}$) over the full angular range of more than 0.52 radians ($> 30 \text{deg}$) and resolution of $0.5 \mu\text{rad}$ (0.1sec) or better;

Compact optical systems with high transmission efficiency and diffraction-limited performance to minimize the weight and size of the sensor unit;

Adaptation of electro-optical sensing or detection devices for star tracker use, to achieve maximum sensitivity (quantum efficiency) and low inherent noise.

Each of these component development areas requires engineering analysis and study to establish preliminary design requirements from which shop drawings suitable for fabrication of test units may be prepared.

Engineering test units will be fabricated and operated under suitable environmental conditions and appropriate loads to evaluate the designs. Engineering tests will be conducted as much as possible at the adapted star tracker level at which the optical and angular measuring devices are integrated.

The results of these development tasks will be reported to the ASM project as requirements and preliminary specifications for use in design, development, test, and evaluation (DDT&E) of the precision star trackers.

e. Resource Requirements

FY	1973	1974		1975
CY	1973		1974	
Manpower	3.0	6.0	8.0	6.0
Fab Shop		—————		
Test Lab		—————		
Funding	\$89,000	\$441,000		\$194,000

f. Target Schedule

FY	1973	1974	1975
CY	1973		1974
Analyses	_____▲		
Design	_____	_____▲	
Fabricate	_____	_____▲	
Test		_____	_____▲
Report			_____▲

3. SRT Requirement No. 3

a. *Title* - Contamination Control and Countermeasures

b. *Status* - Known cleanliness requirements such as Class 100,000 clean assembly and servicing areas for ASM payloads/telescopes, and arrays have been identified. Class 10,000 clean tents have been specified for control of certain critical components when unprotected or unpackaged. Environmental cover and control units that provide inert gas blankets have been identified to protect the payloads during transport between facilities. During pre-launch, provision has been made for maintaining the inert gas blankets after installation of payloads in the Orbiter. Ground operating techniques have been specified to prevent condensation on cooled surfaces.

During the missions, the Orbiter and Sortie Lab are expected to be significant sources of contaminants. The nature and rates of deposit of detrimental contamination from these sources have not been defined. Equipment to reduce or eliminate "harmful" contaminants or countermeasures to disperse or prevent their deposition may be necessary.

c. *Justification* - The scientific fields that are involved in contamination phenomena are essentially:

- 1) Theory of adhesion;
- 2) Theory of valences, molecular structure, and H-bonds;

- 3) Surface catalysis;
- 4) Surface mobility and diffusion of absorbed molecules;
- 5) Theory of nucleation.

Ground work has been laid in these scientific fields to explain observed phenomena, and no new concepts (or theories) have to be developed. It is necessary, however, to perform experiments to predict the extent of the threat of detrimental contamination. The results of these tests will be used to develop equipment to control the emission of contaminants or to disperse emissions without harmful deposition.

The required experiments can be carried out in a laboratory, because a zero-gravity environment is not important for the deposition of matter from the vapor phase. Depending on test results, control equipment to limit emissions or dispersal equipment (or both) must be developed to achieve maximum scientific objectives.

d. Technical Plan

Objectives - To determine the temperatures and contaminant concentration ranges at which detrimental deposition on a given surface can be expected; and to develop equipment concepts for controlling emissions or dispersing those that are detrimental.

Technical Approach - A study of the total problem and an appropriate experimental procedure has been developed and can be applied to provide the test data. The experiments consist of the determination of a dividing line temperature $T_c(P)$ in a (P,T) diagram that divides the area with a deposition rate $r = \frac{dm}{dt} \geq 0$ from the area where $r \leq 0$. $T_c(P)$ is to be determined in the dark and under the UV-light level as experienced in space. P in this context is related to the particle stream of the contaminant under investigation while T is the absolute temperature.

The approach is based on the fact that a surface contamination is "detrimental" only if it is at least a sufficient number of atom layers thick. In this case the influence of the substrate is no longer felt and the contaminant deposits on itself. In the presence of other contaminants and UV light, however, the creation of nucleation centers and the observation of incubation time effects can be expected.

The experiments will give insight into how the deposition of harmful contamination may be avoided. Equipment concepts, procedures, and materials (agents) will be identified and recommended for development as ASM systems if they are required.

e. Resource Requirements

	FY	1973	1974	1975
	CY	1973		1974
Manpower		\$49,600	\$49,600	(Funding Not Estimated)
Test Equipment and Facilities		8,900	8,900	
Materials		2,700		
Funding		\$61,200	\$58,500	

f. Target Schedule

	FY	1973	1974	1975
	CY	1973		1974
Analyses and Planning		—△		
Test		—△		
Evaluate			—△	
Report			—△	
Optional Tasks (If Necessary)			(Funding Not Estimated)	
Design Equipment			---△	
Fabricate			---△	
Test			---△	
Report				---△

IV. COST ESTIMATES

A. COSTING APPROACH, METHODOLOGY, AND RATIONALE

Parametric costing using cost estimating relationships (CERs), cost ratios, and factors in conjunction with detailed estimates was used to price the baseline configuration. Generally, subsystem hardware was priced using CERs, software elements such as project management using cost ratios/factors, and operations elements using detail estimates. Estimates were derived for design, development, test and evaluation (DDT&E), production, and operations. The CERs, cost ratios, and factors used here were developed from Martin Marietta experience on programs such as Skylab and Viking, and from data bank information of other industry programs.

A work breakdown structure (WBS) containing the necessary cost elements as defined by the data requirements (DR) is presented in Fig. IV-2 (in Section F of this part). The cost elements of this WBS will be used in Section B to present nonrecurring (DDR&E) and recurring (production and operations) costs. A definition of the effort encompassed by each WBS cost element is provided by the WBS Dictionary, Table IV-2 (in Section F).

The general ground rules and assumptions used in this pricing are:

- 1) Fiscal 1973 constant dollars;
- 2) Shuttle Lab and Pallet are GFE;
- 3) NASA center cost excluded;
- 4) Experiment and subsystem configurations remain fixed;
- 5) No contingencies or discounts;
- 6) Shuttle operations cost excluded;
- 7) Costs include 10% profit.

The Astronomy Sortie DDT&E cost assumes that the telescopes and arrays are developed by various industry/university sources with the cost of instrument definition and contractor selection a NASA Center responsibility. The remaining cost elements are carried out by a single industry contractor.

DDT&E cost for each subsystem was estimated by the application of the following logic:

BASIC DEVELOPMENT + TEST ARTICLES + TESTING = DDT&E

Cost estimating relationships (CERs) are used at the component level (WBS Level 6 and 7) to build up the basic development cost. Basic development encompasses basic engineering analysis, design, specification preparation, tooling design and fabrication, test criteria, etc.

Development of each telescope and array requires producing one unit, using the unit for tests and checkouts, and updating the same unit for flight. The subsystems are composed of assemblies and components that, in some cases, are qualified and are available off-the-shelf, and in other cases, require extensive development including recommended supporting research and technology (SRT). The inherent project advantages of returning each payload from orbit and the relatively short on-orbit stay times for each flight were considered in recommending limited development tests requiring only one test article in most cases. Conformance with Orbiter certification level requirements for qualification is planned for all "critical" components.

Test article cost is the first unit cost obtained from CERs times the number of test articles computed on a 90% improvement curve. In most instances, the number of test articles is one.

Component and subsystem development testing is estimated at a fixed percentage (22%) of the test article cost.

No spares were specifically allocated to the DDT&E cost category. Spares quantities for the operational phase are scheduled to be built to enable their use during the DDT&E phase, and therefore provide a program cost savings.

Development of GSE, production GSE, and GSE spares is included in the DDT&E phase. GSE development is estimated as a percentage (29%) of the total subsystem development cost, and an operational production set of 116% of the subsystems first unit cost. Two sets of operational GSE were included. GSE spares for the operational phase are priced at 25% of the operational hardware.

The facility cost estimate assumes no new facilities (contractor or government) and the maximum use of existing facilities. Contractor facility cost will be primarily for minor modifications to existing facilities to be used for manufacturing, test, and integration. The estimate is derived from historical experience on programs of a similar nature.

System support and project management costs are estimated as fixed percentages (11% and 7.6%, respectively) of program DDT&E cost. These relationships have been developed from previous contract history.

Production costs for the flight hardware were estimated by using cost estimating relationships. Costs were estimated at the component or subassembly level. This was required to enable a consistent application of a 90% improvement curve due to the variable quantity of each item required for DDT&E, production, and operations (spares). This estimating process for a typical component is as follows: determine the first unit cost using applicable CER; compute DDT&E cost on a 90% curve for units 1 and 2; compute production cost for six units (on a 90% curve - units 3-8); and compute operations cost (spares) for six units (on a 90% curve - units 9-14).

System support and project management costs are estimated at 11% and 7.6 respectively, of the production cost.

The 12-year project duration requires the operation and coordination of activities between three active centers of responsibility: PIC-MSFC; the launch and landing site; and the Space Astronomy Control Facility (SACF).

Each telescope and array will be accepted for integration at the developer's facility and will then be transferred to the Payload Integration Center at MSFC (PIC-MSFC) for integration into the Sortie Lab and pallet, which has been outfitted with the appropriate subsystems. The integrated payloads are tested and checked out to establish flight acceptance at the PIC-MSFC. Support equipment and ground operations are provided to maintain flight readiness with minimum checkout at the launch site.

In addition to initial payload integration, the PIC-MSFC is responsible for refurbishment of the telescopes, arrays, Sortie Labs, and pallets. The refurbished items are subsequently integrated again for a later flight.

The Shuttle launch and landing site is responsible for payload installation into the Orbiter and for prelaunch and postlanding servicing. The PIC-MSFC transient crew provides support for these operations.

The SACF is the scientific center for Astronomy Sortie missions, including principal investigator support of ground and on-orbit operations and problem resolution. The payloads themselves are not handled, serviced, or operated at SACF, but scientific data are processed, stored, analyzed, and disseminated from this center.

Cost estimates for the launch, mission, support, and recovery/refurbishment functions just described were based on the engineering, technical, and administrative manpower level required to sustain the baseline flight schedule. These cost estimates assume the functions are accomplished by the contractor at three separate locations. They further assume that government facilities such as buildings, utilities, office equipment, transportation, gases, and fluids are available at each location at no cost to the contractor.

B. SUMMARY COST PRESENTATIONS

The detailed costs of the Astronomy Sortie missions are summarized in Table IV-1. The table shows total project costs by major hardware item and operations functions in the categories of nonrecurring DDT&E, recurring production, and recurring operations, as well as the total costs. Notice that in developing the GSE (DDT&E), units were fabricated that will satisfy the operations requirements. Therefore, production costs are avoided.

The facilities cost shown in Table IV-1 is for modification of existing facilities to manufacture the subsystems. The costs of facilities for developing the telescopes and arrays, and for operations were not estimated in this study.

Table IV-1 Astronomy Sortie Mission Costs (10⁶ \$)

	<u>DDT&E</u>	<u>Production</u>	<u>Operations</u>	<u>Total</u>
Telescopes	\$ 47.04	\$ 36.98	\$ 37.17	\$121.19
Arrays	39.40	47.32	72.11	158.83
Pointing and Control	18.16	10.53	20.10	48.79
Structures	29.78	12.52	12.14	54.44
Electronics	11.32	4.09	12.91	28.32
Thermal Control	2.32	0.43	0.27	3.02
Ground Support Equipment	21.37	--	3.73	25.10
Facilities	0.25	--	--	0.25
System Support and Integration	18.66	12.31	23.77	54.74
Project Management	14.31	9.44	18.22	41.97
Launch Operations	--	--	14.79	14.79
Mission Operations	--	--	7.95	7.95
Support Operations	--	--	16.06	16.06
Recovery & Refurbishment	--	--	18.84	18.84
Total	\$202.61	\$133.62	\$258.06	\$594.29

Figure IV-1 shows the total funding requirements in each fiscal year of the ASM project by nonrecurring DDT&E, recurring production, and recurring operations categories. The total cost of \$594.3 million for the project requires a peak expenditure of \$156.1 million in fiscal year 1978.

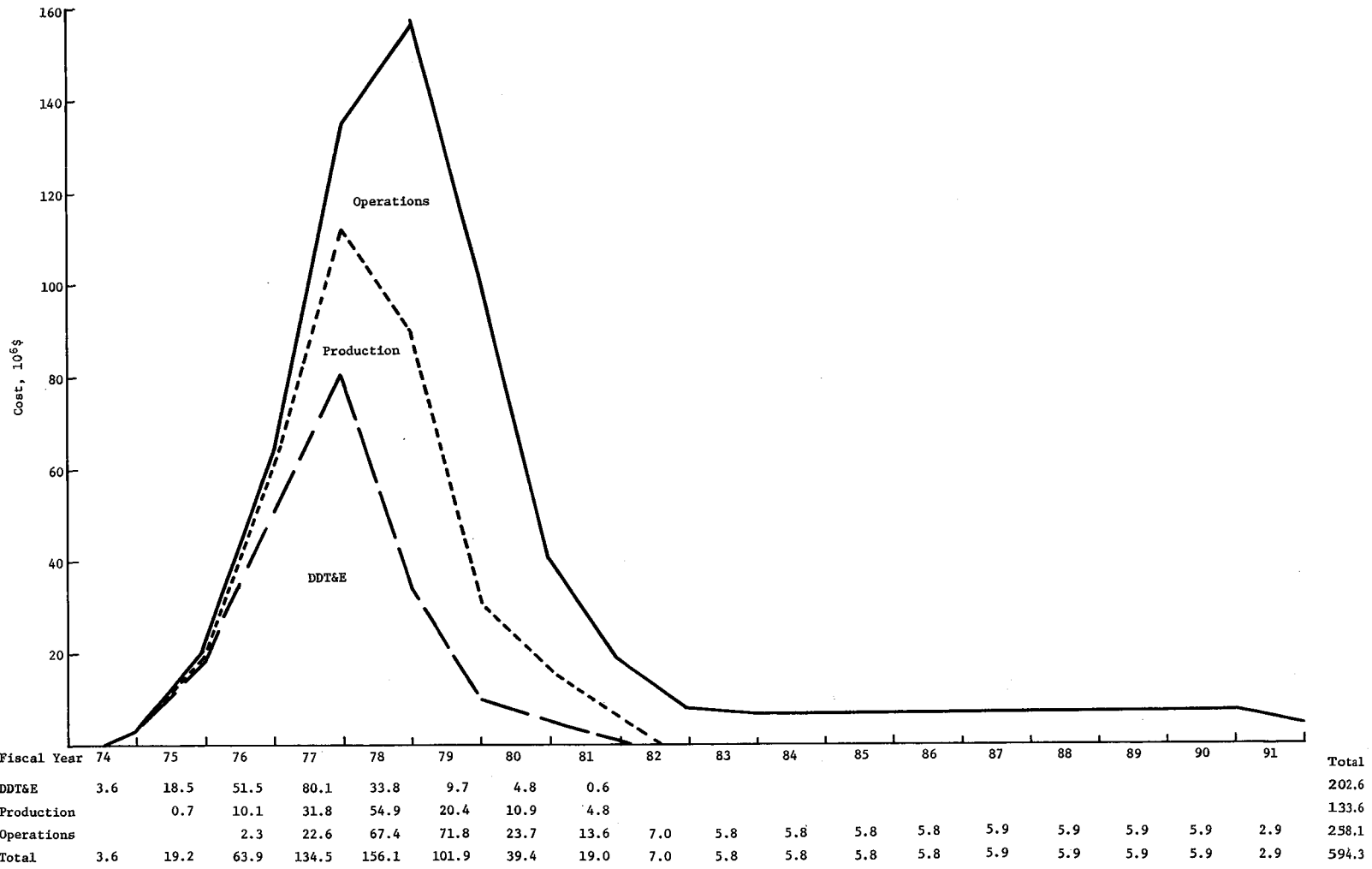


Fig. IV-1 Astronomy Sortie Mission Funding Summary

C. COST ESTIMATES BY WBS ELEMENT

Estimates were prepared for nonrecurring (DDT&E) on Cost Data Form - A(1), for recurring (production) on Cost Data Form - A(2), and for recurring (operations) on Cost Data Form - A(3). These data are presented here at WBS level 4, 5, 6 or 7.

A description of the contents of each column of the form follows:

- 1) Identification Number - The 13-digit WBS number of the item of cost.
- 2) WBS Identification - The alphanumeric nomenclature of the item from the WBS (not limited in length).
- 3) WBS Level - The level at which the element is carried.
- 4) Expected Cost - The cost estimate for the WBS item. For production and operations items, the WBS item cost will be the total cumulative cost for the number of units quantified in the "Number of Units" column.
- 5) Number of Units - The quantity of units for each WBS item used in the production and operations phases of the program.
- 6) Reference Unit - The production sequence number of the first unit that is used in the recurring phase of the program.
- 7) Reference Unit Cost - The cost of the reference unit.
- 8) Learning Index - A numerical index of a learning rate related to the recurring cost.
- 9) T_d - The time (months) to design and develop or produce a WBS item. For nonrecurring category, T_d is the cost duration of the DDT&E activity. For the production and operations activities, T_d is the cost duration of only the reference unit.
- 10) T_s - The lead time (months) measured from the start of cost accrual for the item to the launch milestone. For the production and operations activities T_s will be given for the reference unit.

- 11) Spread Function - An index number representing a cost distribution curve that the estimator recommends for the time phasing of costs over T_d . Standard distributions from Figure 8 of the *Phase A and Phase B Studies Cost Estimates Document* No. MF-030A, were used in some cases. Other distributions were used where applicable.
- 12) Launch Milestone Date - The date used in conjunction with T_s .
- 13) Confidence Rating - A value of 1 through 4 representing the estimator's confidence in the estimate shown in WBS item cost column. The values were obtained by reviewing the criteria presented in the *Phase A and Phase B Studies Cost Estimates Document*, DRD No. MF-030A, Table 1, "Confidence Level Groups for Cost Estimates," and selecting the value most applicable.
- 14) First Unit Cost - The cost to produce theoretical first item. This is the intercept of the learning curve on a log-log plot.

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COST DATA FORM - A(1)
NON-RECURRING (DDT&E)

DATE SEPT 1972
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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	EXPECT. COST	CONFID. RATING	T _d	T _s	SPREAD FUNCT.
01-001-00-00-00-00	ASTRONOMY SORTIE	3	202.61				
	MISSION PROJECT						
01-001-01-00-00-00	PROJECT MANAGEMENT	4	14.31	4	81	96	50/60
01-001-02-00-00-00	SYSTEM SUPPORT &	4	18.66	4	81	96	50/60
	INTEGRATION						
01-001-03-00-00-00	FACILITIES	4	.25	3	12	51	-
01-001-04-00-00-00	GROUND SUPPORT	4	21.37	3	21	27	50/80
	EQUIPMENT						
01-001-05-00-00-00	PAYLOADS	4	148.02				
01-001-05-01-00-00	TELESOPES	5	47.04				
01-001-05-01-01-00	IR TELESCOPE	6	10.50	2	54	69	-
01-001-05-01-02-00	STRATOSCOPE III	6	8.40	2	48	63	-
01-001-05-01-03-00	PHOTOHELIOGRAPH	6	5.16	2	39	57	-
01-001-05-01-04-00	X-RAY TELESCOPE	6	17.65	2	54	66	-
01-001-05-01-05-00	XUV SPECTRO-	6	2.15	2	39	57	-
	HELIOGRAPH						
01-001-05-01-06-00	CORONAGRAPHS	6	2.98	2	39	57	-

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COST DATA FORM - A(1)
NON-RECURRING (DDT&E)

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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	EXPECT. COST	CONFID. RATING	T _d	T _s	SPREAD FUNCT.
01-001-05-03-00-00	POINTING & CONTROL SYSTEM	5	18.16		33	51	50/60
01-001-05-03-01-00	CMG ASSEMBLY	6	.91				
01-001-05-03-01-01	DOUBLE GIMBAL CMGs	7	.77	4			
01-001-05-03-01-02	INVERTERS	7	.14	4			
01-001-05-03-01-03	IMU	7					
01-001-05-03-02-00	COMMON MOUNT ACTUATORS	6	1.32				
01-001-05-03-02-01	AZIMUTH POINTING	7	.65	3			
01-001-05-03-02-02	DEPLOYMENT	7	.67	3			
01-001-05-03-03-00	TELESCOPE GIMBAL ACTUATORS	6	2.16				
01-001-05-03-03-01	ELEVATION POINTING & STABILITY	7	.89	1			
01-001-05-03-03-02	AZIMUTH STABILITY	7	.51	1			

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COST DATA FORM - A(1)
NON-RECURRING (DDT&E)

DATE SEPT 1972
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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	EXPECT. COST	CONFID. RATING	T _d	T _s	SPREAD FUNCT.
01-001-05-04-01-00	COMMON MOUNT	6	7.05				
	ASSEMBLY						
01-001-05-04-01-01	AZIMUTH TABLE	7	1.73	3			
01-001-05-04-01-02	AZIMUTH YOKE	7	2.71	3			
01-001-05-04-01-03	DEPLOYMENT	7	1.20	3			
	YOKE						
01-001-05-04-01-04	DEPLOYMENT	7	1.06	3			
	GEARMOTORS						
	& LAUNCH LOCKS						
01-001-05-04-01-05	JETTISON	7	.35	3			
	EQUIPMENT						
01-001-05-04-02-00	TELESCOPE GIMBAL	6	6.84				
	ASSEMBLY						
01-001-05-04-02-01	OUTER GIMBAL	7	1.62	3			
	RING						
01-001-05-04-02-02	OUTER ROLL	7	2.16	3			
	RING						
01-001-05-04-02-03	INNER ROLL	7	1.37	3			
	RING						

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STUDY TITLE ASTRONOMY SORTIE MISSION DEFINITION STUDY
 CONTRACT NO. NAS8-28144

COST DATA FORM - A(1)
NON-RECURRING (DDT&E)

DATE SEPT 1972
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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	EXPECT. COST	CONFID. RATING	T _d	T _s	SPREAD FUNCT.
01-001-05-04-02-04	ROLL GEAR	7	.10	3			
01-001-05-04-02-05	TELESCOPE P&C PLATFORM	7	.48	3			
01-001-05-04-02-06	GIMBAL GEAR- MOTORS & LAUNCH LOCKS	7	1.11	3			
01-001-05-04-03-00	ARRAY PLATFORM ASSEMBLY	6	4.77				
01-001-05-04-03-01	ARRAY MOUNT	7	3.89	3			
01-001-05-04-03-02	PLATFORM GEAR- MOTORS & LAUNCH LOCKS	7	.88	3			
01-001-05-04-04-00	SUPPORT EQUIPMENT SET	6	4.15				
01-001-05-04-04-01	CMG SUPPORT STRUCTURES	7	.39	3			
01-001-05-04-04-02	WC X-RAY DETECTOR SUPPORTS	7	1.47	3			

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COST DATA FORM - A(1)
NON-RECURRING (DDT&E)

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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	EXPECT. COST	CONFID. RATING	T _d	T _s	SPREAD FUNCT.
01-001-05-04-04-03	γ-RAY SPECT	7	2.29	3			
	HOUSING & EXT						
	MECH.						
01-001-05-04-05-00	SOLAR TELESCOPE	6	6.97				
	HOUSING ASSY						
01-001-05-04-05-01	TUBULAR	7	4.47	3			
	STRUCTURE						
01-001-05-04-05-02	BULKHEADS	7	1.96	3			
01-001-05-04-05-03	SUNSHIELD -	7	.45	3			
	FIBERGLASS						
01-001-05-04-05-04	APERTURE DOORS	7	.06	3			
01-001-05-04-05-05	DOOR ACTUATORS	7	.03	3			
01-001-05-05-00-00	ELECTRONICS	5	11.32		18	36	50/60
01-001-05-05-01-00	CONTROL & DISPLAY	6	7.71	3			
01-001-05-05-02-00	ELECTRICAL	6	2.29				
01-001-05-05-02-01	LOAD CENTER	7	.10	3			
	SWITCH						
01-001-05-05-02-02	FEEDER CABLES	7	2.00	3			
01-001-05-05-02-03	JUNCTION BOX	7	.19	3			

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STUDY TITLE ASTRONOMY SORTIE MISSION DEFINITION STUDY
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COST DATA FORM - A(2)
 RECURRING (PRODUCTION)

DATE: SEPT 1972
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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	NO. OF UNITS	1st UNIT COST T ₁	EXPECTED COST	REF. UNIT	REF. UNIT COST	CONFID. RATING	T _d	T _s	SPREAD FUNCT	LEARN INDEX
01-001-00-00-00-00		3			133.62							
01-001-01-00-00-00	PROJ. MGMT.	4	NA	NA	9.44	NA	NA	4	72	81	50/60	NA
01-001-02-00-00-00	SYS. SUPT.	4	NA	NA	12.31	NA	NA	4	72	81	50/60	NA
01-001-03-00-00-00	FACILITIES	4										
01-001-04-00-00-00	GRD. SUPT. EQUIP.	4										
01-001-05-00-00-00	PAYLOADS	4			84.30							
01-001-05-01-00-00	TELESOPES	5			36.98							
01-001-05-01-01-00	IR TELESCOPE	6	1	12.00	12.00	1	12.00	2	45	54		90%
01-001-05-01-02-00	STRAT III	6	1	7.20	7.20	1	7.20	2	36	45		90%
01-001-05-01-03-00	PHOTOHELIOGRAPH	6	1	4.61	4.61	1	4.61	2	36	45		90%
01-001-05-01-04-00	X-RAY TELE	6	1	8.20	8.20	1	8.20	2	30	39		90%
01-001-05-01-05-00	XUV SPECT	6	1	1.00	1.00	1	1.00	2	30	39		90%
01-001-05-01-06-00	CORONO	6	1	1.95	1.95	1	1.95	2	33	42		90%
01-001-05-01-07-00	MONITORS	6	1	2.02	2.02	1	2.02	3	15	30		90%
01-001-05-02-00-00	ARRAYS	5			47.32							
01-001-05-02-01-00	LG. AREA X-RAY	6	1	4.58	4.58	1	4.58	2	33	45		90%
01-001-05-02-02-00	WC X-RAY	6	1	7.80	7.80	1	7.80	2	39	48		90%
01-001-05-02-03-00	LG. MOD. COLL	6	1	5.18	5.18	1	5.18	2	36	48		90%
01-001-05-02-04-00	NAR. BD SPECT	6	1	10.20	10.20	1	10.20	2	36	48		90%

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STUDY TITLE ASTRONOMY SOURCE MISSION DEFINITION STUDY
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COST DATA FORM - A(2)
RECURRING (PRODUCTION)

DATE: SEPT 1972
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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	NO. OF UNITS	1st UNIT COST T ₁	EXPECTED COST	REF. UNIT	REF. UNIT COST	CONFID. RATING	T _d	T _s	SPREAD FUNCT	LEARN INDEX
01-001-05-02-05-00	COLL P.C. SPECT	6	1	7.30	7.30	1	7.30	2	36	45		90%
01-001-05-02-06-00	γ-RAY SPECT	6	1	4.50	4.50	1	4.50	2	30	39		90%
01-001-05-02-07-00	LOW BACK X-RAY	6	1	7.30	7.30	1	7.30	2	36	48		90%
01-001-05-02-08-00	PROTON FLUX	6	1	.46	.46	1	.46	3	6	24		90%
01-001-05-03-00-00	POINT & CONT.	5			10.53				15	27	50/60	
01-001-05-03-01-00	CMG ASSY	6			3.25							
01-001-05-03-01-01	DB. GIMB. CMG	7	6	.63	2.65	2	.50	4				90%
01-001-05-03-01-02	INVERTER	7	6	.06	.25	2	.05	4				90%
01-001-05-03-01-03	IMU	7	2	.26	.35	5	.18	3				90%
01-001-05-03-02-00	COMMON MT.	6			.85							
01-001-05-03-02-01	AZ POINT	7	4	.16	.47	2	.13	3				90%
01-001-05-03-02-02	DEPLOY	7	4	.13	.38	2	.10	3				90%
01-001-05-03-03-00	TELE. GIMB. ACT	6			1.37							
01-001-05-03-03-01	ELE POINT.	7	4	.22	.64	2	.64	1				90%
01-001-05-03-03-02	AZ STAB	7	4	.13	.38	2	.10	1				90%
01-001-05-03-03-03	ROLL	7	4	.08	.23	2	.06	3				90%
01-001-05-03-03-04	PITCH & YAW	7	2	.08	.12	2	.06	3				90%
01-001-05-03-04-00	ARRAY PLAT.	6	4	.14	.41	2	.11	3				90%
01-001-05-03-05-00	REF. ASSY.	6		*	4.98							
01-001-05-03-05-01	STAR TRACK	7	12	.34	2.65	2	.27	1				90%

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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	NO. OF UNITS	1st UNIT COST T ₁	EXPECTED COST	REF. UNIT	REF. UNIT COST	CONFID. RATING	T _d	T _s	SPREAD FUNCT	LEARN INDEX
01-001-05-03-05-02	TELE. IMU	7	3	.26	.58	2	.58	3				90%
01-001-05-03-05-03	SUN SENS.	7	1	.74	.59	2	.59	4				90%
01-001-05-03-05-04	STAR TRACK	7	1	.28	.22	2	.22	3				90%
01-001-05-03-05-05	CORR TRACK	7	1	.76	.61	2	.61	3				90%
01-001-05-04-00-00	STRUCTURES	5			12.52				12	24	50/60	
01-001-05-04-01-00	COMM. MOUNT	6			4.83							
01-001-05-04-01-01	AZ. TABLE	7	4	.37	1.08	2	.30	3				90%
01-001-05-04-01-02	AZ. YOKE	7	4	.58	1.69	2	.46	3				90%
01-001-05-04-01-03	DEPLOY. YOKE	7	4	.26	.76	2	.21	3				90%
01-001-05-04-01-04	GEAR & LOCK	7	8	.21	1.10	3	.16	3				90%
01-001-05-04-01-05	JETT EQUIP	7	4	.07	.20	2	.06	3				90%
01-001-05-04-02-00	TELE GIMB. ASSY	6			3.65							
01-001-05-04-02-01	OUT. GIMB.	7	3	.35	.78	2	.28	3				90%
01-001-05-04-02-02	OUT. ROLL	7	3	.47	1.05	2	.38	3				90%
01-001-05-04-02-03	INNER ROLL	7	3	.30	.67	2	.24	3				90%
01-001-05-04-02-04	ROLL GEAR	7	3	.02	.04	2	.02	3				90%
01-001-05-04-02-05	P&C PLAT.	7	3	.10	.22	2	.08	3				90%
01-001-05-04-02-06	GEAR & LOCK	7	6	.22	.89	3	.16	3				90%
01-001-05-04-03-00	ARRAY PLAT ASSY	6			1.93							
01-001-05-04-03-01	ARRAY MT.	7	2	.84	1.29	2	.67	3				90%

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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	NO. OF UNITS	1st UNIT COST T ₁	EXPECTED COST	REF. UNIT	REF. UNIT COST	CONFID. RATING	T _d	T _s	SPREAD FUNCT	LEARN INDEX
01-001-05-04-03-02	GEAR & LOCK	7	4	.22	.64	2	.18	3				90%
01-001-05-04-04-00	SUPT. EQUIP.	6			.88							
01-001-05-04-04-01	CMG SUPT	7	6	.06	.23	4	.04	3				90%
01-001-05-04-04-02	W.C. MT.	7	1	.32	.26	2	.26	3				90%
01-001-05-04-04-03	γ-RAY HOUS.	7	1	.49	.39	2	.39	3				90%
01-001-05-04-05-00	SOL. TELE. HOUS	6			1.23							
01-001-05-04-05-01	TUB. STRUCT	7	1	.97	.78	2	.78	3				90%
01-001-05-04-05-02	BULKHEADS	7	1	.42	.34	2	.34	3				90%
01-001-05-04-05-03	SUNSHIELD	7	1	.10	.08	2	.08	3				90%
01-001-05-04-05-04	APER. DOOR	7	6	.006	.02	2	.005	3				90%
01-001-05-04-05-05	DOOR ACT.	7	6	.004	.01	2	.003	3				90%
01-001-05-05-00-00	ELECTRONICS	5			4.09				12	24	50/60	
01-001-05-05-01-00	CONT. & DISP.	6	2	1.57	2.42	2	1.26	3				90%
01-001-05-05-02-00	ELECTRICAL	6			.81							
01-001-05-05-02-01	LOAD SW.	7	12	.03	.22	2	.02	3				90%
01-001-05-05-02-02	CABLES	7	1	.50	.50	1	.50	3				90%
01-001-05-05-02-03	JUNC. BOX	7	2	.06	.09	2	.05	3				90%
01-001-05-05-03-00	DATA	6			.86							
01-001-05-05-03-01	INTER. UNIT	7	8	.02	.10	2	.02	3				90%
01-001-05-05-03-02	COAX	7	2	.04	.07	1	.04	3				90%

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COST DATA FORM - A(2)
 RECURRING (PRODUCTION)

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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	NO. OF UNITS	1st UNIT COST T ₁	EXPECTED COST	REF. UNIT	REF. UNIT COST	CONFID. RATING	T _d	T _s	SPREAD FUNCT	LEARN INDEX
01-001-05-05-03-03	INSTRU. BOX	7	2	.10	.15	2	.08	3				90%
01-001-05-05-03-04	DATA PROCES.	7	8	.10	.54	2	.08	3				90%
01-001-05-06-00-00	THERMAL CONT.	6	2	.38	.43	2	.30	3	6	18	50/60	90%

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 RECURRING (OPERATIONS)

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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	NO. OF UNITS	EXPECT COST	REF. UNIT	REF UNIT COST	CONFID. RATING	T _d	T _s	SPREAD. POINT	LEAD% INDEX
01-001-05-02-06-00	γ-RAY SPECT	6	2	6.93	2	3.60	2	42	33	-	90%
01-001-05-02-07-00	LOW BACK γ-RAY	6	2	11.23	2	5.84	2	51	42	-	90%
01-001-05-03-00-00	POINT & CONT	5		20.10				27	21	50/60	
01-001-05-03-01-00	GMG ASSY	6		3.96							
01-001-05-03-01-01	DB GIMB CMG	7	9	3.33	8	.39	4				90%
01-001-05-03-01-02	INVERTER	7	5	.18	8	.04	4				90%
01-001-05-03-01-03	IMU	7	3	.45	15	.15	3				90%
01-001-05-03-02-00	COMMON MT	6		2.14							
01-001-05-03-02-01	AZ POINT	7	18	1.66	6	.10	3				90%
01-001-05-03-02-02	DEPLOY.	7	6	.48	6	.09	3				90%
01-001-05-03-03-00	TELE GIMB ACT.	6		4.77							
01-001-05-03-03-01	ELE POINT.	7	18	2.28	6	.14	1				90%
01-001-05-03-03-02	AZ STAB.	7	18	1.35	6	.09	1				90%
01-001-05-03-03-03	ROLL	7	18	.83	6	.05	3				90%
01-001-05-03-03-04	PITCH & YAW	7	6	.31	4	.06	3				90%
01-001-05-03-04-00	ARRAY PLAT	6	18	1.45	6	.09	3				90%
01-001-05-03-05-00	REF ASSY	6		7.78							
01-001-05-03-05-01	STAR TRACK.	7	24	4.27	14	.19	1				90%
01-001-05-03-05-02	TELE IMU	7	6	.95	7	.17	3				90%
01-001-05-03-05-03	SUN SENS	7	2	1.07	3	.55	4				90%

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IDENTIFICATION NUMBER	WBS IDENTIFICATION	WBS LEVEL	NO. OF UNITS	EXPECT COST	REF. UNIT	REF UNIT COST	CONFID. RATING	T ₂	T ₁	SPREAD FACTOR	LEARN INDEX
01-001-05-04-04-00	SUPT EQUIP.	6		1.24							
01-001-05-04-04-01	CMG SUPT	7	2	.07	10	.04	3				90%
01-001-05-04-04-02	WC MOUNT	7	2	.46	3	.24	3				90%
01-001-05-04-04-03	X-RAY HOUSING	7	2	.71	3	.36	3				90%
01-001-05-04-05-00	SOL TELE HOUS	6		1.15							
01-001-05-04-05-01	TUB. STRUCT	7	1	.72	3	.72	3				90%
01-001-05-04-05-02	BULKHEADS	7	1	.31	3	.31	3				90%
01-001-05-04-05-03	SUNSHIELD	7	1	.07	3	.07	3				90%
01-001-05-04-05-04	APER DOOR	7	6	.02	13	.003	3				90%
01-001-05-04-05-05	DOOR ACT.	7	12	.03	13	.002	3				90%
01-001-05-05-00-00	ELECTRONICS	5		12.91				24	18		
01-001-05-05-01-00	CONT & DISPLAY	6	12	11.62	4	1.10	3				90%
01-001-05-05-02-00	ELECTRICAL	6		.64							
01-001-05-05-02-01	LOAD SWITCH	7	12	.20	14		3				90%
01-001-05-05-02-02	CABLES	7	1	.40	2	.40	3				90%
01-001-05-05-02-03	JUNC BOX	7	1	.04	4	.04	3				90%
01-001-05-05-03-00	DATA	6		.65							
01-001-05-05-03-01	INTER UNIT	7	8	.09	10	.01	3				90%
01-001-05-05-03-02	COAX	7	1	.03	3	.03	3				90%
01-001-05-05-03-03	INSTRU BOX	7	1	.07	4	.07	3				90%

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D. TECHNICAL CHARACTERISTICS DATA

Technical Characteristics Data (TCD) Form B sheets were prepared for each of the telescopes, arrays, and subsystems at WBS levels 5 and 6. The TCDs are arranged here in order of increasing number. The data were used in estimating costs of each item. A description of the information in each column of the TCD form is as follows:

- 1) WBS Identification Number - The 13-digit WBS code number of the item.
- 2) WBS Identification - The alphanumeric nomenclature of the item from the WBS.
- 3) Quantity or Value - The numerical quantity or value of the characteristic (Column 5) under consideration; where no characteristic is identified, quantity refers to the WBS item and identification number.
- 4) Units of Measure - The identification of the units of measure associated with the characteristics (Column 5) under consideration; where no characteristic is identified, units of measure applies to the WBS item and identification number.
- 5) Characteristics - The identification of the technical property under consideration.
- 6) Notes - Comments or explanations to clarify any of the information presented.

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-01-00-00	TELESCOPES	1	UNIT	1-m INFRARED TELESCOPE	
		1	UNIT	1.2-m STRATOSCOPE III	
		1	UNIT	1-m PHOTOHELIOGRAPH	
		1	UNIT	0.32-m X-RAY TELESCOPE	
		1	UNIT	0.25-m X UV SPECTROHELIOGRAPH	
		1	UNIT	CORONAGRAPH ASSEMBLY (2.5-cm AND 4.0-cm CORONAGRAPH)	
		4	UNITS	MONITORS	

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(1) WBS IDENTIFICATION NUMBER	(2) WBS IDENTIFICATION	(3) QUANTITY OR VALUE	(4) UNITS OF MEASURE	(5) CHARACTERISTICS	(6) NOTES
01-001-05-01-01-00	INFRARED TELESCOPE	1.0	m	PRIMARY APERTURE	CASSEGRAIN OPTICS
		5.0	min	FIELD OF VIEW	
		f/10		SYSTEM F NUMBER	
		0.7-1000	MICRONS	WAVELENGTH RANGE	
		1	UNIT	INTERFEROMETER	
		1	UNIT	LINEAR DETECTOR ARRAY	
		3.2X1.6D	m	SIZE	
		1600	kg	TOTAL WEIGHT	
		(3525)	(LB)		

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(1) WBS IDENTIFICATION NUMBER	(2) WBS IDENTIFICATION	(3) QUANTITY OR VALUE	(4) UNITS OF MEASURE	(5) CHARACTERISTICS	(6) NOTES
01-001-05-01-02-00	STRATOSCOPE III	1.20	m	PRIMARY APERTURE	RITCHEY-CHRETION
		6.0	MIN	FIELD OF VIEW	(WITH 2X RELAY)
		1.1	-	PRIMARY f NUMBER	
		1.2	-	SYSTEM f NUMBER	
		900 TO 20,000	ANG-STROMS	SPECTRAL RANGE	
		2	UNIT	FIELD CAMERAS	} 2 OR 3 SENSORS PER MISSION
		2	UNIT	SPECTROGRAPHS	
		1	UNIT	POLARIMETER	
		1	UNIT	FIELD VIEWING MONITOR	
		1	UNIT	INTERNAL CLOSED-LOOP GUIDING SYSTEM	
		4.2X1.9D	m	SIZE	
		(5.9X 1.9D)	(m)	(SUN SHADE EXTENDED)	
		1800 (3962)	kg (lb)	TOTAL WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF (4) MEASURE	CHARACTERISTICS (5)	NOTES (6)	
01-001-05-01-03-00	PHOTOHELIOGRAPH	1.0	m	PRIMARY APERTURE	GREGORIAN OPTICS	
		3.0	MIN	FIELD OF VIEW		
		3.85	-	PRIMARY f NUMBER		
		50.0	-	OVERALL f NUMBER		
		2000 TO 7000	ANG- STROMS	SPECTRAL RANGE		
		3	UNIT	FILM CAMERAS		
		1	UNIT	SPECTROGRAPH		
		1	UNIT	INTERNAL FINE POINTING AND STABILITY SYSTEM		THE INTERNAL POINTING AND STABILIZATION SYSTEM WILL BE A SIGNIFICANT DE- VELOPMENT ITEM
		4.6X1.9 X1.42	m	SIZE		
		570	kg	TOTAL WEIGHT		
(1260)	(1b)					

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-01-04-00	X-RAY TELESCOPE	32	cm	APERTURE	GRAZING INCIDENCE
		10	MIN	FIELD OF VIEW	
		10		OVERALL f NUMBER	
		2 TO 100	ANG- STROMS	SPECTRAL RANGE	
		1	UNIT	IMAGING SYSTEM	
		1	UNIT	CRYSTAL SPECTRO- METER	
		1	UNIT	PROPORTIONAL COUNTER	
		1	UNIT	FILM CAMERA	
		4.6X0.7D	m	SIZE	
		392 (862)	kg (lb)	TOTAL WEIGHT	

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(1) WBS IDENTIFICATION NUMBER	(2) WBS IDENTIFICATION	(3) QUANTITY OR VALUE	(4) UNITS OF MEASURE	(5) CHARACTERISTICS	(6) NOTES
01-001-05-01-05-00	XUV SPECTROHELIOGRAPH	25	cm	APERTURE	CONCAVE GRATING-COLLECTING OPTICS
		32	MIN	FIELD OF VIEW	
		12	-	SYSTEM f NUMBER	
		170 TO 650	ANG-STROMS	SPECTRAL RANGE	
		1 3.4x1.3 X0.76	UNIT	FILM CAMERA	
		430 (948)	kg (1b)	TOTAL WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-01-06-00	CORONAGRAPHS IC-INNER CORONAGRAPH OC-OUTER CORONAGRAPH	IC / OC 2.45/4.0 3.25/15 12.9/ 2.25 4000 TO 7000 2 3.8X1.2X 0.7 430 (947)	cm deg - ANG- STROMS UNIT m kg (1b)	APERTURE(S) FIELD OF VIEW SYSTEM f NUMBER SPECTRAL RANGE FILM CAMERAS SIZE TOTAL WEIGHT	REFRACTIVE OPTICS

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF (4) MEASURE	CHARACTERISTICS (5)	NOTES (6)
01-001-05-01-07-00	MONITORS	1	UNIT	XUV MONITOR OPTICAL-MECHANICAL ASSEMBLY	SOLAR TELESCOPE GROUP
		1.43X.26 X.24	m	SIZE	
		45.3 (100)	kg (1b)	WEIGHT	
		2	w	POWER	
		1	UNIT	CONTROL UNIT	
		10	w	POWER	
		37X37X 16	cm	SIZE	
		11 (24)	kg (1b)	TOTAL WEIGHT	
		1	UNIT	XRT MONITOR	SOLAR TELESCOPE GROUP
		20DX 122L	cm	SIZE	
		45.3 (100)	kg (1b)	TOTAL WEIGHT	
		1	UNIT	H-ALPHA MONITOR	SOLAR TELESCOPE GROUP
		15	W	POWER	
		160X35.5 X25.4	cm	SIZE	
		56 (124)	kg (1b)	TOTAL WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF (4) MEASURE	CHARACTERISTICS (5)	NOTES (6)
01-001-05-01-07-00 (CON'T)	MONITORS (CON'T)	1 30 15X15X 94 48 (106)	UNIT w cm kg (lb)	FIELD VIEWING POWER SIZE TOTAL WEIGHT	IR TELESCOPE (ONLY)

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WBS LEVEL 5

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-02-00-00	ARRAYS	1	UNIT	LARGE AREA X-RAY DETECTOR	
		1	UNIT	WIDE COVERAGE X-RAY DETECTOR	
		1	UNIT	LARGE MODULATION COLLIMATOR	
		1	UNIT	NARROW BAND SPECTROMETER/POLARIMETER	
		1	UNIT	COLLIMATED PLANE CRYSTAL SPECTROMETER	
		1	UNIT	GAMMA-RAY SPECTROMETER	
		1	UNIT	LOW BACKGROUND GAMMA-RAY DETECTOR	
		1	UNIT	PROTON FLUX DETECTOR	

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(1) WBS IDENTIFICATION NUMBER	(2) WBS IDENTIFICATION	(3) QUANTITY OR VALUE	(4) UNITS OF MEASURE	(5) CHARACTERISTICS	(6) NOTES
01-001-05-02-01-00	LARGE AREA X-RAY DETECTOR	0.1 TO 100 1.15 6 1 2.4X1.8 X0.5 315 (695)	KEV deg UNIT UNIT m kg (1b)	ENERGY BAND FIELD OF VIEW DETECTOR MODULES DATA PROCESSOR SIZE TOTAL WEIGHT	

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(1) WBS IDENTIFICATION NUMBER	(2) WBS IDENTIFICATION	QUANTITY OR (3) VALUE	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-02-02-00	WIDE COVERAGE X-RAY DETECTOR(S)	2 TO 200 180 154 1 1.2X2D 250 (550)	KEV deg UNIT UNIT m kg (1b)	ENERGY BAND FIELD OF VIEW DETECTOR DATA PROCESSOR SIZE TOTAL WEIGHT	DIVIDED INTO TWO QUARTER-SPHERES FOR HEMISPHERICAL COVERAGE

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-02-03-00	LARGE MODULATION COLLIMATOR	0.1 TO 100	KEV	ENERGY BAND	ARGON/CARBON DIOXIDE
		2.9	deg	FIELD OF VIEW	
		6	UNIT	DETECTOR MODULES	
		1	UNIT	DATA PROCESSOR	
		1	UNIT	GAS SUPPLY	
		2.9X2.3 X0.85	m	SIZE	
		375 (826)	kg (1b)	TOTAL WEIGHT	

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(1) WBS IDENTIFICATION NUMBER	(2) WBS IDENTIFICATION	QUANTITY OR (3) VALUE	UNITS OF (4) MEASURE	(5) CHARACTERISTICS	(6) NOTES
01-001-05-02-04-00	NARROW BAND SPECTROMETER/ POLARIMETER	5.94 TO 8.37 1.0 9 1 2.5X2.5 X0.6 543 (1197)	KEV deg UNIT UNIT m kg (1b)	ENERGY BAND FIELD OF VIEW DETECTOR MODULES DATA PROCESSOR SIZE TOTAL WEIGHT	(NINE SPECIFIC EMISSIONS)

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01-001-05-02-05-00	COLLIMATED PLANE CRYSTAL SPECTROMETER	0.5 TO 10 30 3 1 1.22X 1.33X 1.84 260.8 (574)	KEV deg UNIT UNIT m kg (1b)	ENERGY BAND FIELD OF VIEW DETECTOR MODULES DATA PROCESSOR SIZE TOTAL WEIGHT	

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01-001-05-02-06-00	GAMMA RAY SPECTROMETER	0.06 TO 10 72 1 1 1 0.34X 0.34X x 0.7 155 (341)	MEV deg UNIT UNIT UNIT m kg (1b)	ENERGY BAND FIELD OF VIEW DETECTOR CRYO REFRIGERATOR DATA PROCESSOR SIZE TOTAL WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-02-07-00	LOW BACKGROUND GAMMA RAY DETECTOR	0.3 TO 10 110 4 1 1.4X1.4 X0.5 994 (2190)	MEV deg UNIT UNIT m kg (1b)	ENERGY BAND FIELD OF VIEW DETECTOR MODULES DATA PROCESSOR SIZE TOTAL WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF (4) MEASURE	CHARACTERISTICS (5)	NOTES (6)
01-001-05-02-08-00	PROTON FLUX DETECTOR	-	-	HIGH ENERGY ALERT	WARNS OF SOUTH ATLANTIC ANOMALY
		90	deg	FIELD OF VIEW	(TWO 45° CONES)
		0.4X0.4 X0.4	m	SIZE	
		13.5	kg	TOTAL WEIGHT	
		(30)	(1b)		

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-03-00-00	POINTING & CONTROL SYSTEM	1	UNIT PER PAYLOAD		
01-001-05-03-01-00	CMG ASSEMBLY	1	ASSEMBLY PER PAYLOAD	3 DG CMGS 3 INVERTERS 1 IMU	
01-001-05-03-02-00	COMMON MOUNT ACTUATORS	2	UNITS PER PAYLOAD	AZIMUTH POINTING DEPLOYMENT	
01-001-05-03-03-00	TELESCOPE GIMBAL ACTUATORS	1	UNIT PER PAYLOAD	ELEVATION POINTING & STABILITY AZIMUTH STABILITY ROLL	
		1	UNIT PER SOLAR PAYLOAD	ELEVATION POINTING & STABILITY AZI-MUTH STABILITY ROLL PITCH & YAW (CORONAGRAPHS)	
01-001-05-03-04-00	ARRAY PLATFORM ACTUATORS	1	UNIT PER STELLAR PAYLOAD	ELEVATION POINTING	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-03-05-00	REFERENCE ASSEMBLY	1	UNIT PER PAYLOAD	STRAPDOWN STAR TRACKERS TELESCOPE IMU FINE SUN SENSOR PRECISION BORE-SIGHTED STAR TRACKER CORRELATION TRACKER	2 SETS OF 4 FOR SOLAR PAYLOAD; 1 SET OF 4 FOR STELLAR PAYLOADS. 2 REQ'D FOR SOLAR 1 REQ'D FOR STELLAR CORONAGRAPHS IR TELESCOPE SOLAR GROUP

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF (4) MEASURE	CHARACTERISTICS (5)	NOTES (6)
01-001-05-03-01-00	CMG ASSEMBLY	1	ASSEMBLY PER PAYLOAD		
		150	WATTS	AVERAGE POWER	
01-001-05-03-01-01	DOUBLE GIMBAL CMGS	3 2300	UNITS ft-lb- sec	MOMENTUM CAPABIL- ITY PER CMG	SKYLAB TOTAL MOMENTUM OF 6900 ft-lb-sec
		191 (420)	kg (1b)	UNIT WEIGHT	
01-001-05-03-01-02	INVERTERS	3 25	UNITS kg	UNIT WEIGHT	SKYLAB INCLUDES INVERTER HEATERS
		(55)	(1b)		
01-001-05-03-01-03	IMU	1	UNIT		ELECTRONICS TO INTEGRATE RATE AND ATTITUDE DATA OF SHUTTLE
		6.8 (15)	kg (1b)	UNIT WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF (4) MEASURE	CHARACTERISTICS (5)	NOTES (6)
01-001-05-03-02-00	COMMON MOUNT ACTUATORS	2	UNITS PER PAYLOAD		
01-001-05-03-02-01	AZIMUTH POINTING	1	UNIT	ROLLING ELEMENT BEARING TYPE	
		11 5	ft-lb sec	STALL TORQUE POSITION INDICA- TION ACCURACY	
		15.9 (35)	kg (1b)	UNIT WEIGHT	
01-001-05-03-02-02	DEPLOYMENT	2	UNITS	ROLLING ELEMENT BEARING TYPE	
		90 30	ft-lb min	STALL TORQUE POSITION INDICA- TION ACCURACY	
		13.6 (30)	kg (1b)	UNIT WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-03-03-00	TELESCOPE GIMBAL ACTUATORS	1 (SEE NOTE)	SET PER PAYLOAD	USE FOR IR, S III, OR PHG	ADDITIONAL SET REQUIRED FOR SOLAR GROUP
01-001-05-03-03-01	ELEVATION POINTING & STABILITY	2	UNITS	ROLLING ELEMENT ELEVATION; FLEX PIVOT STABILIZATION	
		11	ft-lb	STALL TORQUE ELEVATION	
		7	ft-lb	STALL TORQUE STABILIZATION	
		5	sec	POSITION INDICATION ACCURACY	
		28.1 (62)	kg (lb)	UNIT WEIGHT	
01-001-05-03-03-02	AZIMUTH STABILITY	2	UNITS	FLEX PIVOT BEARING	
		7	ft-lb	STALL TORQUE	
		5	sec	POSITION INDICATION ACCURACY	
		15.9 (35)	kg (lb)	UNIT WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-03-03-03	ROLL	1 2.7 30 8.6 (19)	UNIT ft-lb min kg (1b)	ROLLING ELEMENT BEARING STALL TORQUE POSITION INDICATION ACCURACY UNIT WEIGHT	

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01-001-05-03-03-00	TELESCOPE GIMBAL ACTUATORS	1 (SEE NOTE)	SET	USE FOR SOLAR GROUP TELESCOPES	SEE OTHER SET REQUIRED FOR IR, SIII OR PHG
01-001-05-03-03-01	ELEVATION POINTING & STABILITY	2 11 7 5 28.1 (62)	UNITS ft-lb ft-lb sec kg (lb)	ROLLING ELEMENT ELEVATION; FLEX PIVOT STABILIZATION STALL TORQUE ELEVATION STALL TORQUE STABILIZATION POSITION INDICATION ACCURACY UNIT WEIGHT	
01-001-05-03-03-02	AZIMUTH STABILITY	2 7 5 15.9 (35)	UNITS ft-lb sec kg (lb)	FLEX PIVOT BEARING STALL TORQUE POSITION INDICATOR ACCURACY UNIT WEIGHT	
01-001-05-03-03-03	ROLL	1 2.7 30 8.6 (19)	UNIT ft-lb min kg (lb)	ROLLING ELEMENT BEARING STALL TORQUE POSITION INDICATION ACCURACY UNIT WEIGHT	

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01-001-05-03-03-04	PITCH & YAW	2 9.1 (20)	UNITS kg (1b)	CORONAGRAPHS UNIT WEIGHT	
01-001-05-03-04-00	ARRAY PLATFORM ACTUATOR	1	SET	USE ON STELLAR PAYLOADS FOR ARRAYS	NOT REQUIRED FOR SOLAR
01-001-05-03-04-01	ELEVATION POINTING	2 11 5 13.6 (30)	UNITS ft-lb sec kg (1b)	ROLLING ELEMENT BEARING STALL TORQUE POSITION INDICATION ACCURACY UNIT WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF (4) MEASURE	CHARACTERISTICS (5)	NOTES (6)
01-001-05-03-05-00	REFERENCE ASSEMBLY	1 (SEE NOTE)	UNIT		SECOND UNIT WITH FINE SUN SENSOR & CORRELATION TRACKER REQUIRED FOR SOLAR
01-001-05-03-05-01	STRAPDOWN STAR TRACKERS	4	UNITS	OPTICS & ELECTRONICS	
		15 (33)	kg (1b)	UNIT WEIGHT	
01-001-05-03-05-02	TELESCOPE IMU	1	UNIT	ELECTRONICS	
		6.8 (15)	kg (1b)	UNIT WEIGHT	
01-001-05-03-05-03	FINE SUN SENSOR	1	UNIT	OPTICAL-MECHANICAL; PREAMP ASSEMBLY; SIGNAL CONDITIONER; CONTROL ELECTRONICS ASSEMBLY	REQUIRED FOR CORONAGRAPHS ONLY. ATM
		11 24.5 (54)	watts kg (1b)	POWER UNIT WEIGHT	INCLUDES ELECTRONICS
01-001-05-03-05-04	PRECISION BORESIGHTED STAR TRACKER	1	UNIT		REQUIRED FOR IR TELESCOPE ONLY
		11.3 (25)	kg (1b)	UNIT WEIGHT	
01-001-05-03-05-05	CORRELATION TRACKER	1	UNIT		REQUIRED FOR SOLAR GROUP ONLY
		25 54.5 (120)	watts kg (1b)	POWER UNIT WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-04-00-00	STRUCTURES				
01-001-05-04-01-00	COMMON MOUNT ASSEMBLY	2	ASSEMBLIES	1 AZIMUTH TABLE	
			PER PAYLOAD	1 AZIMUTH YOKE	
				1 DEPLOYMENT YOKE	
				2 DEPLOYMENT GEAR-	
				MOTORS & LAUNCH	
				LOCKS	
				1 SET JETTISON	
				EQUIPMENT	
01-001-05-04-02-00	TELESCOPE GIMBAL ASSEMBLY	1 (SEE NOTE)	ASSEMBLY	1 OUTER GIMBAL RING	SOLAR PAYLOAD RE-
			PER PAYLOAD	1 OUTER ROLL RING	QUIRES TWO ASSEM-
				1 INNER ROLL RING	BLIES
				1 ROLL GEAR	
				1 TELESCOPE P&C	
				PLATFORM	
				1 SET GIMBAL GEAR-	
				MOTORS & LAUNCH	
				LOCKS	
01-001-05-04-03-00	ARRAY PLATFORM ASSEMBLY	1 (SEE NOTE)	ASSEMBLY	1 ARRAY MOUNT	REQUIRED FOR STEL-
			PER PAYLOAD	1 SET PLATFORM	LAR PAYLOADS ONLY
				GEARMOTORS &	
				LAUNCH LOCKS	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF (4) MEASURE	CHARACTERISTICS (5)	NOTES (6)
01-001-05-04-04-00	SUPPORT EQUIPMENT SET	1	SET PER PAYLOAD	3 CMG SUPPORT STRUCTURES 1 SET WIDE COVER- AGE X-RAY DETECTOR SUPPORTS 1 GAMMA RAY SPECTROMETER HOUS- ING AND EXTENSION MECHANISM	REQUIRED FOR ALL PAYLOADS REQUIRED FOR STEL- LAR PAYLOADS ONLY REQUIRED FOR STEL- LAR PAYLOADS ONLY
01-001-05-04-05-00	SOLAR TELESCOPE HOUSING ASSEMBLY	1	UNIT	1 TUBULAR STRUC- TURE 2 BULKHEADS 1 FIBERGLASS SUN- SHIELD 6 APERTURE DOORS 6 APERTURE DOOR ACTUATORS	REQUIRED FOR SOLAR GROUP ONLY

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-04-01-00	COMMON MOUNT ASSEMBLY	2	ASSEMBLIES PER PAYLOAD		
01-001-05-04-01-01	AZIMUTH TABLE	1 0.69x 1.27x 1.27 111 (244)	UNIT m kg (1b)	BASIC STRUCTURE WITHOUT ACTUATORS ENVELOPE SIZE UNIT WEIGHT	
01-001-05-04-01-02	AZIMUTH YOKE	1 1.01x 2.54x 3.35 172 (380)	UNIT m kg (1b)	BASIC STRUCTURE WITHOUT ACTUATORS ENVELOPE SIZE UNIT WEIGHT	
01-001-05-04-01-03	DEPLOYMENT YOKE	1 0.31x 4.0 x 3.1 76 (168)	UNIT m kg (1b)	BASIC STRUCTURE WITHOUT ACTUATORS ENVELOPE SIZE UNIT WEIGHT	

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(1) WBS IDENTIFICATION NUMBER	(2) WBS IDENTIFICATION	(3) QUANTITY OR VALUE	(4) UNITS OF MEASURE	(5) CHARACTERISTICS	(6) NOTES
01-001-05-04-01-04	DEPLOYMENT GEARMOTORS & LAUNCH LOCKS	2 23.6 (52)	UNITS kg (1b)	UNIT WEIGHT	INCLUDES GIMBAL RING SUPPORTS
01-001-05-04-01-05	JETTISON EQUIPMENT	1 20.4 (45)	UNIT kg (1b)	UNIT WEIGHT	
01-001-05-04-02-00	TELESCOPE GIMBAL ASSEMBLY	1 (SEE NOTE)	ASSEMBLY PER PAYLOAD		SOLAR PAYLOAD REQUIRES 2 ASSEMBLIES
01-001-05-04-02-01	OUTER GIMBAL RING	1 100 (220)	UNIT kg (1b)	ALUMINUM RING UNIT WEIGHT	
01-001-05-04-02-02	OUTER ROLL RING	1 133 (294)	UNIT kg (1b)	ALUMINUM RING UNIT WEIGHT	
01-001-05-04-02-03	INNER TOLL RING	1 84.3 (186)	UNIT kg (1b)	ALUMINUM RING UNIT WEIGHT	
01-001-05-04-02-04	ROLL GEAR	1 6.4 (14)	UNIT kg (1b)	UNIT WEIGHT	
01-001-05-04-02-05	TELESCOPE P&C PLATFORM	1 30.4 (67)	UNIT kg (1b)	UNIT WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF (4) MEASURE	CHARACTERISTICS (5)	NOTES (6)
01-001-05-04-02-06	GIMBAL GEARMOTORS & LAUNCH LOCKS	2 24.5 (54)	UNITS kg (1b)	UNIT WEIGHT	
01-001-05-04-03-00	ARRAY PLATFORM ASSEMBLY	1	ASSEMBLY		REQUIRED FOR STELLAR PAYLOADS ONLY
01-001-05-04-03-01	ARRAY MOUNT	1 200 (440)	UNIT kg (1b)	BASIC STRUCTURE WITHOUT ACTUATORS UNIT WEIGHT	
01-001-05-04-03-02	PLATFORM GEARMOTORS & LAUNCH LOCKS	2 24 (53)	UNITS kg (1b)	UNIT WEIGHT	

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WBS IDENTIFICATION (1) NUMBER	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-04-04-00	SUPPORT EQUIPMENT SET	1	SET PER PAYLOAD		
01-001-05-04-04-01	CMG SUPPORT STRUCTURES	3 14.7 (32.5)	UNITS PER SET kg (1b)	BASIC STRUCTURE UNIT WEIGHT	INCLUDES INVERTER SUPPORT STRUCTURES
01-001-05-04-04-02	WIDE COVERAGE X-RAY DETECTOR MOUNT	2 77 (170)	UNITS PER SET kg (1b)	BASIC STRUCTURE UNIT WEIGHT	REQUIRED FOR STEL- LAR PAYLOADS ONLY
01-001-05-04-04-03	GAMMA RAY SPECTROMETER HOUSING AND EXTENSION MECHANISM	1 476 (1050)	UNIT kg (1b)	BASIC STRUCTURE UNIT WEIGHT	REQUIRED FOR STEL- LAR PAYLOADS 3AC & 4AC ONLY

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(1) WBS IDENTIFICATION NUMBER	(2) WBS IDENTIFICATION	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-04-05-00	SOLAR TELESCOPE HOUSING ASSEMBLY	1	ASSEMBLY	BASIC STRUCTURE	REQUIRED FOR SOLAR GROUP ONLY
01-001-05-04-05-01	TUBULAR STRUCTURE	1 302 (290)	UNIT kg (1b)	BASIC STRUCTURE UNIT WEIGHT	
01-001-05-04-05-02	BULKHEADS	1 132 (290)	UNITS kg (1b)	BASIC STRUCTURE UNIT WEIGHT	INCLUDES FITTINGS AND PARTITIONS
01-001-05-04-05-03	FIBER GLASS SUNSHIELD	1 30.4 (67)	UNIT kg (1b)	UNIT WEIGHT	
01-001-05-04-05-04	APERTURE DOORS	6 1.81 (4)	UNITS kg (1b)	BASIC STRUCTURE UNIT WEIGHT	
01-001-05-04-05-05	DOOR ACTUATORS	6 0.91 (2)	UNITS kg (1b)	ELECTRO-MECHANICAL UNIT WEIGHT	

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-05-00-00 01-001-05-05-01-00	ELECTRONIC CONTROL & DISPLAY	1	UNIT	1 CB/DISTRIBUTOR PANEL 2 MULTIPURPOSE CRTS 1 SYMBOL GENERATOR 1 FUNCTION KEY-BOARD 1 ALPHANUMERIC KEYBOARD 2 KEYBOARD ENCODERS 1 MICROFILM VIEWER 1 EVENT TIMER 1 MISSION TIMER 1 THREE AXIS CONTROLLER 2 ANNUNCIATOR BANKS 1 RECORDER	EQUIPMENT IS INSTALLED IN SORTIE LAB FOR ALL PAYLOADS
01-001-05-05-02-00	ELECTRICAL	1	UNIT	6 LOAD CENTER SWITCHES - FEEDER CALBES 1 JUNCTION BOX	REQUIRED FOR ALL PAYLOADS
01-001-05-05-03-00	DATA	1	UNIT	4 DATA BUS INTER-FACE UNIT 1 COAX DATA BUS 1 PALLET INSTR BOX 4 DATA PROCESSOR	REQUIRED FOR ALL PAYLOADS

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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR (3) VALUE	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-05-01-00	CONTROL & DISPLAY	1 415 149 (329)	UNIT PER PAYLOAD W kg (1b)	INTEGRATED CONCEPT POWER UNIT WEIGHT	INSTALLED IN SORTIE LAB
01-001-05-05-01-01	CB/DISTRIBUTOR PANEL	1	UNIT		
01-001-05-05-01-02	MULTIPURPOSE CRTs	2	UNITS	VIDEO	ALPHANUMERIC STATIC GRAPHIC
01-001-05-05-01-03	SYMBOL GENERATOR	1	UNIT	GENERATE SYMBOLS, CHARACTERS, VECTORS, RASTER VIDEO	
01-001-05-05-01-04	FUNCTION KEYBOARD	1	UNIT	FUNCTIONAL CATEGORY DATA	
01-001-05-05-01-05	ALPHANUMERIC KEYBOARD	1	UNIT		
01-001-05-05-01-06	KEYBOARD ENCODERS	2	UNITS		
01-001-05-05-01-07	MICROFILM VIEWER	1	UNIT	READ PROCEDURAL TYPE DATA	
01-001-05-05-01-08	EVENT TIMER	1	UNIT		
01-001-05-05-01-09	MISSION TIMER	1	UNIT		
01-001-05-05-01-10	THREE-AXIS CONTROLLER	1	UNIT	INSTRUMENT POINTING	
01-001-05-05-01-11	ANNUNCIATOR BANK	2	UNITS	VISUAL ALERTING	
01-001-05-05-01-12	RECORDER	1	UNIT	MULTI CHANNEL	

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01-001-05-05-02-00	ELECTRICAL				
01-001-05-05-02-01	LOAD CENTER SWITCH	6 10 x 5 x 20	UNITS CM W	SIZE POWER UNIT WEIGHT	
01-001-05-05-02-02	FEEDER CABLES	70 (155) 60 (133)	kg (1b) kg (1b)	PAYLOAD WEIGHT SOLAR PAYLOAD WEIGHT STELLAR	
01-001-05-05-02-03	JUNCTION BOX	1 4.54 (10)	UNIT kg (1b)	WEIGHT	

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(1) WBS IDENTIFICATION NUMBER	(2) WBS IDENTIFICATION	(3) QUANTITY OR VALUE	(4) UNITS OF MEASURE	(5) CHARACTERISTICS	(6) NOTES
01-001-05-05-03-00	DATA				
01-001-05-05-03-01	DATA BUS INTERFACE UNIT	4	UNITS	REMOTE COMMAND & MULTIPLEXING	ALL PAYLOADS
		9.5	W	POWER	
		10 x	CM	EVNELOPE SIZE	
		8 x			
		18			
		1.81	kg	UNIT WEIGHT	
		(4)	(lb)		
01-001-05-05-03-02	COAX DATA BUS	122	M	LENGTH	ALL PAYLOADS
		9.1	kg	PAYLOAD WEIGHT	
		(20)	(lb)		
01-001-05-05-03-03	PALLET INSTRUMENTATION BOX	1	UNIT	STATUS AND DYNAMIC ENVIRONMENT MONITOR	ALL PAYLOADS
		5.0	watts	POWER	
		2.26	kg	UNIT WEIGHT	
		(5)	(lb)		
01-001-05-05-03-04	DATA PROCESSOR	4	UNITS		ALL PAYLOADS
		3.0	watts	POWER	
		2.26	kg	UNIT WEIGHT	
		(5)	(lb)		

IV-65

STUDY TITLE ASMDS
 CONTRACT NO. NAS8-28144

TECHNICAL CHARACTERISTICS DATA FORM B

WBS LEVEL 5 & 6

DATE SEPT 1972
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WBS IDENTIFICATION NUMBER (1)	WBS IDENTIFICATION (2)	QUANTITY OR VALUE (3)	UNITS OF MEASURE (4)	CHARACTERISTICS (5)	NOTES (6)
01-001-05-06-00-00	THERMAL CONTROL	1	UNIT		ALL PAYLOADS
01-001-05-06-01-00	THERMAL COATING	5.45 (12)	kg (1b)	293 TYPE WHITE PAINT PAYLOAD WEIGHT	APPLIED TO ALL SURFACES OF DEPLOYMENT YOKE
01-001-05-06-02-00	MULTILAYER INSULATION	59 (130)	kg (1b)	PALLET EQUIPMENT PAYLOAD WEIGHT	ALL PAYLOADS
		62.1 (137)	kg (1b)	SOLAR TELESCOPE HOUSING PAYLOAD WEIGHT	SOLAR PAYLOAD ONLY
		22.6 (50)	kg (1b)	ARRAY PLATFORM PAYLOAD WEIGHT	STELLAR PAYLOADS ONLY

E. TOTAL PROGRAM FUNDING SCHEDULE

The time-phased estimates of the costs required to accomplish the total program are presented here on Data Form C. The WBS lower level cost estimates were time-phased by fiscal year against the proposed development or production schedule by estimated distribution of costs or by using the appropriate spreading function. Spreading functions were selected from those presented in *Phase A and Phase B studies Cost Estimates Document*, DRD No. MF-030A, Figure 8, "Idealized Cost Distribution Curves." The results were then summarized to develop the funding schedules of higher levels.

STUDY TITLE ASTRONOMY SORTIE MISSION DEFINITION STUDY
 CONTRACT NO. NAS8-28144 FUNDING SCHEDULE DATA FORM C

NON-RECURRING (ODT&E)
 RECURRING (PRODUCTION)
 RECURRING (OPERATIONS)

DATE SEPT 1972
 PAGE 1 OF 3

PROJECT WBS ITEMS	FY 74	FY 75	FY 76	FY 77	FY 78	FY 79	FY 80	FY 81	FY _____
ASTRONOMY SORTIE MISSION	3.58	18.51	51.46	80.10	33.79	9.72	4.80	.65	202.61
PROJECT MANAGEMENT	.31	1.98	6.03	4.16	1.16	.54	.11	.02	
SYSTEM SUPPORT & INTEG.	.40	2.58	7.87	5.42	1.52	.70	.14	.03	
FACILITIES	.05	.20							
GROUND SUPPORT EQUIP.				9.20	12.11	.06			
IR TELESCOPE	1.25	3.00	2.65	2.25	1.35				
STRATOSCOPE III				1.10	2.60	2.40	1.70	.60	
PHOTOHELIOGRAPH		1.50	2.00	1.50	.16				
X-RAY TELESCOPE	1.57	3.73	5.90	4.50	1.95				
XUV SPECTROHELIOGRAPH		.75	.85	.40	.15				
CORONAGRAPHS		.95	.95	.89	.19				
MONITORS				.05	.15				
LARGE AREA X-RAY				.80	1.78	1.52	.85		
WIDE COVERAGE X-RAY		.25	1.17	.83					
LARGE MODULATION COLLIM.			.80	1.65	2.15	1.95	.40		
NARROW BAND SPECTRO/POLAR.			.90	2.35	2.20	.85			
COLLIM. P.C. SPECTROMETER				.50	1.30	1.70	1.60		
GAMMA RAY SPECTROMETER		.80	1.75	2.10	2.65				
LOW BACKGROUND X-RAY		.90	2.10	2.40	1.10				
PROTON FLUX DETECTOR					.05				
POINTING & CONTROL		1.87	10.37	5.84	.08				
STRUCTURES			7.14	22.15	.49				
ELECTRONICS			.98	10.05	.29				
THERMAL CONTROL				1.96	.36				

STUDY TITLE ASTRONOMY SORTIE MISSION DEFINITION STUDY

CONTRACT NO. NAS8-28144

FUNDING SCHEDULE DATA FORM C

NON-RECURRING (DDT&E)
 RECURRING (PRODUCTION)
 RECURRING (OPERATIONS)

DATE SEPT 1972
 PAGE 2 OF 3

PROJECT WBS ITEMS	FY <u>75</u>	FY <u>76</u>	FY <u>77</u>	FY <u>78</u>	FY <u>79</u>	FY <u>80</u>	FY <u>81</u>
ASTRONOMY SORTIE MISSION	.70	10.14	31.75	54.89	20.42	10.91	4.81
PROJECT MANAGEMENT	.02	.27	2.12	3.81	2.05	1.03	.14
SYSTEM SUPPORT & INTEG.	.03	.86	3.60	4.50	2.19	1.01	.12
IR TELESCOPE	.65	2.85	3.00	3.50	2.00		
STRATOSCOPE III					2.00	2.50	2.70
PHOTOHELIOGRAPH		1.26	1.75	1.60			
X-RAY TELESCOPE		.50	2.75	4.95			
XUV SPECTROHELIOGRAPH		.15	.35	.50			
CORONAGRAPHS		.45	.65	.85			
MONITORS				1.78	.24		
LARGE AREA X-RAY				.63	1.58	1.92	.45
WIDE COVERAGE X-RAY		2.20	2.60	2.10	.90		
LARGE MODULATION COLLIM.			.30	1.45	1.78	1.65	
NARROW BAND SPECTRO/POLAR.			2.80	3.70	3.70		
COLLIM. P.C. SPECTROMETER				.80	2.30	2.80	1.40
GAMMA RAY SPECTROMETER			1.80	1.80	.90		
LOW BACKGROUND X-RAY		1.60	2.40	2.70	.60		
PROTON FLUX DETECTOR				.28	.18		
POINTING & CONTROL			4.51	6.02			
STRUCTURES			2.35	10.17			
ELECTRONICS			.77	3.32			
THERMAL CONTROL				.43			

F. WORK BREAKDOWN STRUCTURE (WBS)

The final WBS dictionary and diagram are presented in this section. This WBS is compatible with the breakdown that was used in estimating costs.

The dictionary (Table IV-2) is a listing in numerical order of the functions and hardware which must be developed for the ASM project.

Figure IV-2 is the diagram showing the relationship of these elements in a family tree. In the dictionary, functions and support hardware shown only as level 4 on the diagram are further identified to level 5. Components and assemblies of the payloads (a level 4 item on the diagram) are identified to level 5 and 6 on the diagrams and in the dictionary. Further, the components and assemblies of subsystems are identified to level 7 in the dictionary.

Table IV-2 WBS Dictionary

WBS IDENTIFICATION NUMBER						WBS IDENTIFICATION
LEVEL 2	LEVEL 3	LEVEL 4	LEVEL 5	LEVEL 6	LEVEL 7	
0 1	0 0 0	0 0	0 0	0 0	0 0	SHUTTLE SORTIE MISSION PROGRAM
0 1	0 0 1	0 0	0 0	0 0	0 0	ASTRONOMY SORTIE MISSION PROJECT
0 1	0 0 1	0 1	0 0	0 0	0 0	PROJECT MANAGEMENT
0 1	0 0 1	0 1	0 1	0 0	0 0	PROGRAM CONTROL
0 1	0 0 1	0 1	0 2	0 0	0 0	CONFIGURATION MANAGEMENT
0 1	0 0 1	0 1	0 3	0 0	0 0	CONTRACTUAL DATA MANAGEMENT
0 1	0 0 1	0 2	0 0	0 0	0 0	SYSTEM SUPPORT & INTEGRATION
0 1	0 0 1	0 2	0 1	0 0	0 0	SYSTEMS ANALYSIS
0 1	0 0 1	0 2	0 2	0 0	0 0	PAYLOAD INTEGRATION
0 1	0 0 1	0 2	0 3	0 0	0 0	PROGRAM INTEGRATION
0 1	0 0 1	0 2	0 4	0 0	0 0	SAFETY AND RELIABILITY
0 1	0 0 1	0 2	0 5	0 0	0 0	QUALITY ASSURANCE
0 1	0 0 1	0 3	0 0	0 0	0 0	FACILITIES
0 1	0 0 1	0 3	0 1	0 0	0 0	CONTRACTOR
0 1	0 0 1	0 3	0 2	0 0	0 0	GOVERNMENT
0 1	0 0 1	0 4	0 0	0 0	0 0	GROUND SUPPORT EQUIPMENT
0 1	0 0 1	0 4	0 1	0 0	0 0	ELECTRICAL & ELECTRONIC
0 1	0 0 1	0 4	0 2	0 0	0 0	STRUCTURAL & MECHANICAL
0 1	0 0 1	0 4	0 3	0 0	0 0	OPTICAL
0 1	0 0 1	0 4	0 4	0 0	0 0	TRANSPORT & HANDLING
0 1	0 0 1	0 5	0 0	0 0	0 0	PAYLOADS
0 1	0 0 1	0 5	0 1	0 0	0 0	TELESCOPES
0 1	0 0 1	0 5	0 1	0 1	0 0	IR TELESCOPE
0 1	0 0 1	0 5	0 1	0 2	0 0	STRATOSCOPE III
0 1	0 0 1	0 5	0 1	0 3	0 0	PHOTOHELIOGRAPH
0 1	0 0 1	0 5	0 1	0 4	0 0	X-RAY TELESCOPE
0 1	0 0 1	0 5	0 1	0 5	0 0	XUV SPECTROHELIOGRAPH
0 1	0 0 1	0 5	0 1	0 6	0 0	CORONAGRAPHS
0 1	0 0 1	0 5	0 1	0 7	0 0	MONITORS
0 1	0 0 1	0 5	0 2	0 0	0 0	ARRAYS
0 1	0 0 1	0 5	0 2	0 1	0 0	LARGE AREA X-RAY DETECTOR
0 1	0 0 1	0 5	0 2	0 2	0 0	WIDE COVERAGE X-RAY DETECTOR
0 1	0 0 1	0 5	0 2	0 3	0 0	LARGE MODULATION COLLIMATOR
0 1	0 0 1	0 5	0 2	0 4	0 0	NARROW BAND SPECTRO/POLARIM
0 1	0 0 1	0 5	0 2	0 5	0 0	COLLIMATED PC SPECTROMETER
0 1	0 0 1	0 5	0 2	0 6	0 0	GAMMA-RAY SPECTROMETER
0 1	0 0 1	0 5	0 2	0 7	0 0	LOW BACKGROUND γ -RAY DETECTOR
0 1	0 0 1	0 5	0 2	0 8	0 0	PROTON FLUX DETECTOR

Table IV-2 (cont)

WBS IDENTIFICATION NUMBER						WBS IDENTIFICATION							
LEVEL 2	LEVEL 3	LEVEL 4	LEVEL 5	LEVEL 6	LEVEL 7								
0	1	0	0	1	0	5	0	3	0	0	0	0	POINTING & CONTROL SYSTEM
0	1	0	0	1	0	5	0	3	0	1	0	0	CMG ASSEMBLY
0	1	0	0	1	0	5	0	3	0	1	0	1	DOUBLE GIMBAL CMGs
0	1	0	0	1	0	5	0	3	0	1	0	2	INVERTERS
0	1	0	0	1	0	5	0	3	0	1	0	3	IMU
0	1	0	0	1	0	5	0	3	0	2	0	0	COMMON MOUNT ACTUATORS
0	1	0	0	1	0	5	0	3	0	2	0	1	AZIMUTH POINTING
0	1	0	0	1	0	5	0	3	0	2	0	2	DEPLOYMENT
0	1	0	0	1	0	5	0	3	0	3	0	0	TELESCOPE GIMBAL ACTUATORS
0	1	0	0	1	0	5	0	3	0	3	0	1	ELEVATION POINTING & STABILITY
0	1	0	0	1	0	5	0	3	0	3	0	2	AZIMUTH STABILITY
0	1	0	0	1	0	5	0	3	0	3	0	3	ROLL
0	1	0	0	1	0	5	0	3	0	3	0	4	PITCH & YAW (CORONAGRAPHS)
0	1	0	0	1	0	5	0	3	0	4	0	0	ARRAY PLATFORM ACTUATOR
0	1	0	0	1	0	5	0	3	0	4	0	1	ELEVATION POINTING
0	1	0	0	1	0	5	0	3	0	5	0	0	REFERENCE ASSEMBLY
0	1	0	0	1	0	5	0	3	0	5	0	1	STRAPDOWN STAR TRACKERS
0	1	0	0	1	0	5	0	3	0	5	0	2	TELESCOPE IMU
0	1	0	0	1	0	5	0	3	0	5	0	3	FINE SUN SENSOR
0	1	0	0	1	0	5	0	3	0	5	0	4	BORESIGHTED STAR TRACKER-PRECISION
0	1	0	0	1	0	5	0	3	0	5	0	5	CORRELATION TRACKER
0	1	0	0	1	0	5	0	4	0	0	0	0	STRUCTURES
0	1	0	0	1	0	5	0	4	0	1	0	0	COMMON MOUNT ASSEMBLY
0	1	0	0	1	0	5	0	4	0	1	0	1	AZIMUTH TABLE
0	1	0	0	1	0	5	0	4	0	1	0	2	AZIMUTH YOKE
0	1	0	0	1	0	5	0	4	0	1	0	3	DEPLOYMENT YOKE
0	1	0	0	1	0	5	0	4	0	1	0	4	DEPLOYMENT GEARMOTORS & LAUNCH LOCKS
0	1	0	0	1	0	5	0	4	0	1	0	5	JETTISON EQUIPMENT

Table IV-2 (cont)

WBS IDENTIFICATION NUMBER							WBS IDENTIFICATION
LEVEL 2	LEVEL 3	LEVEL 4	LEVEL 5	LEVEL 6	LEVEL 7		
0 1	0 0 1	0 5	0 4	0 2	0 0	TELESCOPE GIMBAL ASSEMBLY	
0 1	0 0 1	0 5	0 4	0 2	0 1	OUTER GIMBAL RING	
0 1	0 0 1	0 5	0 4	0 2	0 2	OUTER ROLL RING	
0 1	0 0 1	0 5	0 4	0 2	0 3	INNER ROLL RING	
0 1	0 0 1	0 5	0 4	0 2	0 4	ROLL GEAR	
0 1	0 0 1	0 5	0 4	0 2	0 5	TELESCOPE P & C PLATFORM	
0 1	0 0 1	0 5	0 4	0 2	0 6	GIMBAL GEARMOTORS & LAUNCH LOCKS	
0 1	0 0 1	0 5	0 4	0 3	0 0	ARRAY PLATFORM ASSEMBLY	
0 1	0 0 1	0 5	0 4	0 3	0 1	ARRAY MOUNT	
0 1	0 0 1	0 5	0 4	0 3	0 2	PLATFORM GEARMOTORS & LAUNCH LOCKS	
0 1	0 0 1	0 5	0 4	0 4	0 0	SUPPORT EQUIPMENT SET	
0 1	0 0 1	0 5	0 4	0 4	0 1	CMG SUPPORT STRUCTURES	
0 1	0 0 1	0 5	0 4	0 4	0 2	WC X-RAY DETECTOR MOUNT	
0 1	0 0 1	0 5	0 4	0 4	0 3	γ-RAY SPECT HOUSING & EXT MECH	
0 1	0 0 1	0 5	0 4	0 5	0 0	SOLAR TELESCOPE HOUSING ASSY	
0 1	0 0 1	0 5	0 4	0 5	0 1	TUBULAR STRUCTURE	
0 1	0 0 1	0 5	0 4	0 5	0 2	BULKHEADS	
0 1	0 0 1	0 5	0 4	0 5	0 3	SUNSHIELD-FIBERGLASS	
0 1	0 0 1	0 5	0 4	0 5	0 4	APERTURE DOORS	
0 1	0 0 1	0 5	0 4	0 5	0 5	DOOR ACTUATORS	
0 1	0 0 1	0 5	0 5	0 0	0 0	ELECTRONIC	
0 1	0 0 1	0 5	0 5	0 1	0 0	CONTROL & DISPLAY	
0 1	0 0 1	0 5	0 5	0 1	0 1	CB/DISTRIBUTOR PANEL	
0 1	0 0 1	0 5	0 5	0 1	0 2	MULTIPURPOSE CRT	
0 1	0 0 1	0 5	0 5	0 1	0 3	SYMBOL GENERATOR	
0 1	0 0 1	0 5	0 5	0 1	0 4	FUNCTION KEYBOARD	
0 1	0 0 1	0 5	0 5	0 1	0 5	ALPHANUMERIC KEYBOARD	
0 1	0 0 1	0 5	0 5	0 1	0 6	KEYBOARD ENCODER	
0 1	0 0 1	0 5	0 5	0 1	0 7	MICROFILM VIEWER	
0 1	0 0 1	0 5	0 5	0 1	0 8	EVENT TIMER	
0 1	0 0 1	0 5	0 5	0 1	0 9	MISSION TIMER	
0 1	0 0 1	0 5	0 5	0 1	1 0	THREE-AXIS CONTROLLER	
0 1	0 0 1	0 5	0 5	0 1	1 1	ANNUNCIATOR BANK	
0 1	0 0 1	0 5	0 5	0 1	1 2	RECORDER	

Table IV-2 (concl)

WBS IDENTIFICATION NUMBER							WBS IDENTIFICATION
LEVEL 2	LEVEL 3	LEVEL 4	LEVEL 5	LEVEL 6	LEVEL 7		
0	1	0 0 1	0 5	0 5	0 2	0 0	ELECTRICAL
0	1	0 0 1	0 5	0 5	0 2	0 1	LOAD CENTER SWITCH
0	1	0 0 1	0 5	0 5	0 2	0 2	FEEDER CABLES
0	1	0 0 1	0 5	0 5	0 2	0 3	JUNCTION BOX
0	1	0 0 1	0 5	0 5	0 3	0 0	DATA
0	1	0 0 1	0 5	0 5	0 3	0 1	DATA BUS INTERFACE UNIT
0	1	0 0 1	0 5	0 5	0 3	0 2	COAX DATA BUS
0	1	0 0 1	0 5	0 5	0 3	0 3	PALLET INSTRUMENTATION BOX
0	1	0 0 1	0 5	0 5	0 3	0 4	DATA PROCESSOR
0	1	0 0 1	0 5	0 6	0 0	0 0	THERMAL CONTROL
0	1	0 0 1	0 5	0 6	0 1	0 0	THERMAL COATING
0	1	0 0 1	0 5	0 6	0 2	0 0	MULTILAYER INSULATION
0	1	0 0 1	0 6	0 0	0 0	0 0	LAUNCH OPERATIONS
0	1	0 0 1	0 6	0 1	0 0	0 0	PRELAUNCH
0	1	0 0 1	0 6	0 2	0 0	0 0	LAUNCH
0	1	0 0 1	0 7	0 0	0 0	0 0	MISSION OPERATIONS
0	1	0 0 1	0 7	0 1	0 0	0 0	MISSION CONTROL
0	1	0 0 1	0 7	0 2	0 0	0 0	MISSION PLANNING
0	1	0 0 1	0 8	0 0	0 0	0 0	SUPPORT OPERATIONS
0	1	0 0 1	0 8	0 1	0 0	0 0	EXPERIMENT CREW TRAINING
0	1	0 0 1	0 8	0 2	0 0	0 0	SUSTAINING ENGINEERING
0	1	0 0 1	0 9	0 2	0 0	0 0	GSE MAINTENANCE
0	1	0 0 1	0 9	0 0	0 0	0 0	RECOVERY & REFURBISHMENT OPERATIONS
0	1	0 0 1	0 9	0 1	0 0	0 0	TELESCOPES
0	1	0 0 1	0 9	0 2	0 0	0 0	ARRAYS
0	1	0 0 1	0 9	0 3	0 0	0 0	SUBSYSTEMS

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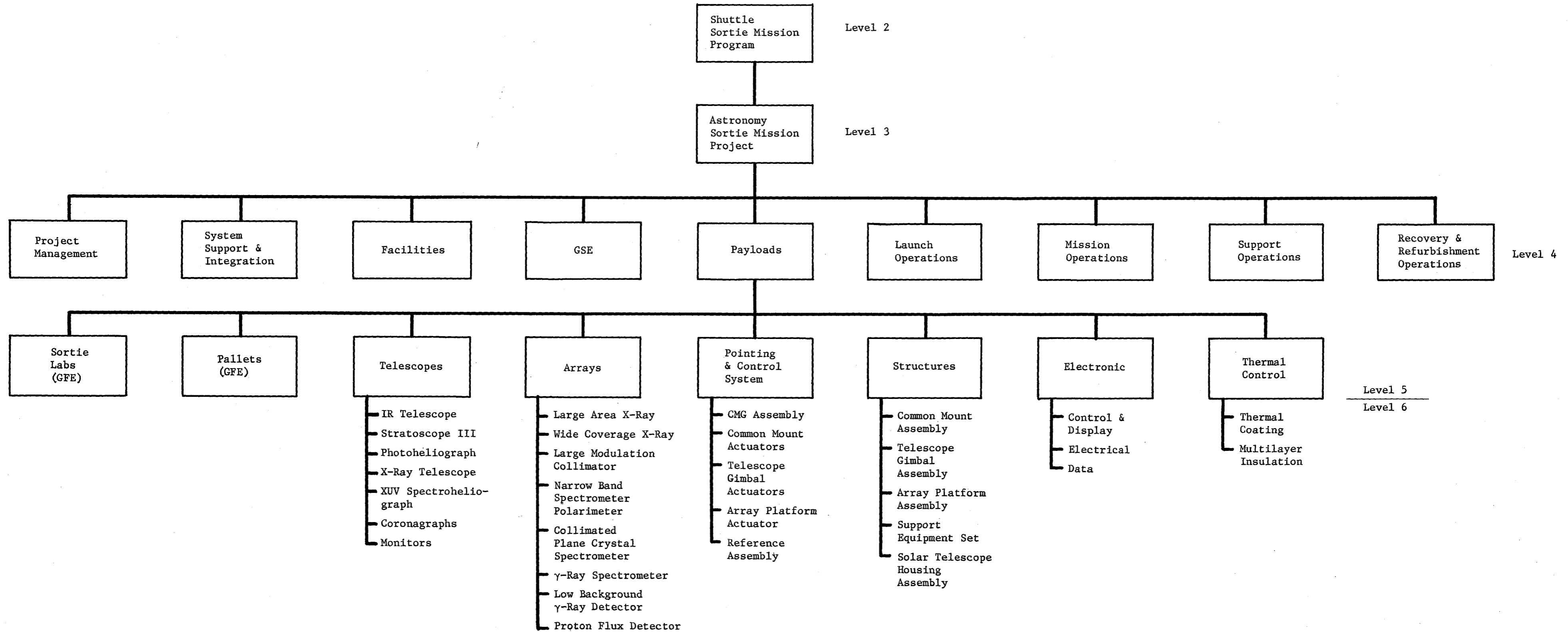


Fig. IV-2 Work Breakdown Structure (WBS) Diagram